



Damage evaluation and measurement via correlation techniques

*(Schadensbewertung und Messung mit
Korrelationstechniken)*

François HILD & Eikology team

Damage / Fracture

Challenges

- Need for reliable kinematic fields
- Robust and validated models

Outline

- Evaluation of damage via DIC and DVC
- Design of discriminating experiments
(e.g., concrete)
- Summary and perspectives

Damage / Fracture

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(e.g., concrete)
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Digital Image Correlation

Measurement of optical flow

$$I_0(\mathbf{x}) \approx I_t(\mathbf{x} + \mathbf{u}(\mathbf{x}))$$

Local approach

$$\eta_c^2(\mathbf{u}) = \sum_{\text{ZOI}} [I_0(\mathbf{x}) - I_t(\mathbf{x} + \mathbf{u})]^2$$

$$(I_0 * I_t)(\mathbf{u}) = \sum_{\text{ZOI}} I_0(\mathbf{x}) I_t(\mathbf{x} + \mathbf{u})$$

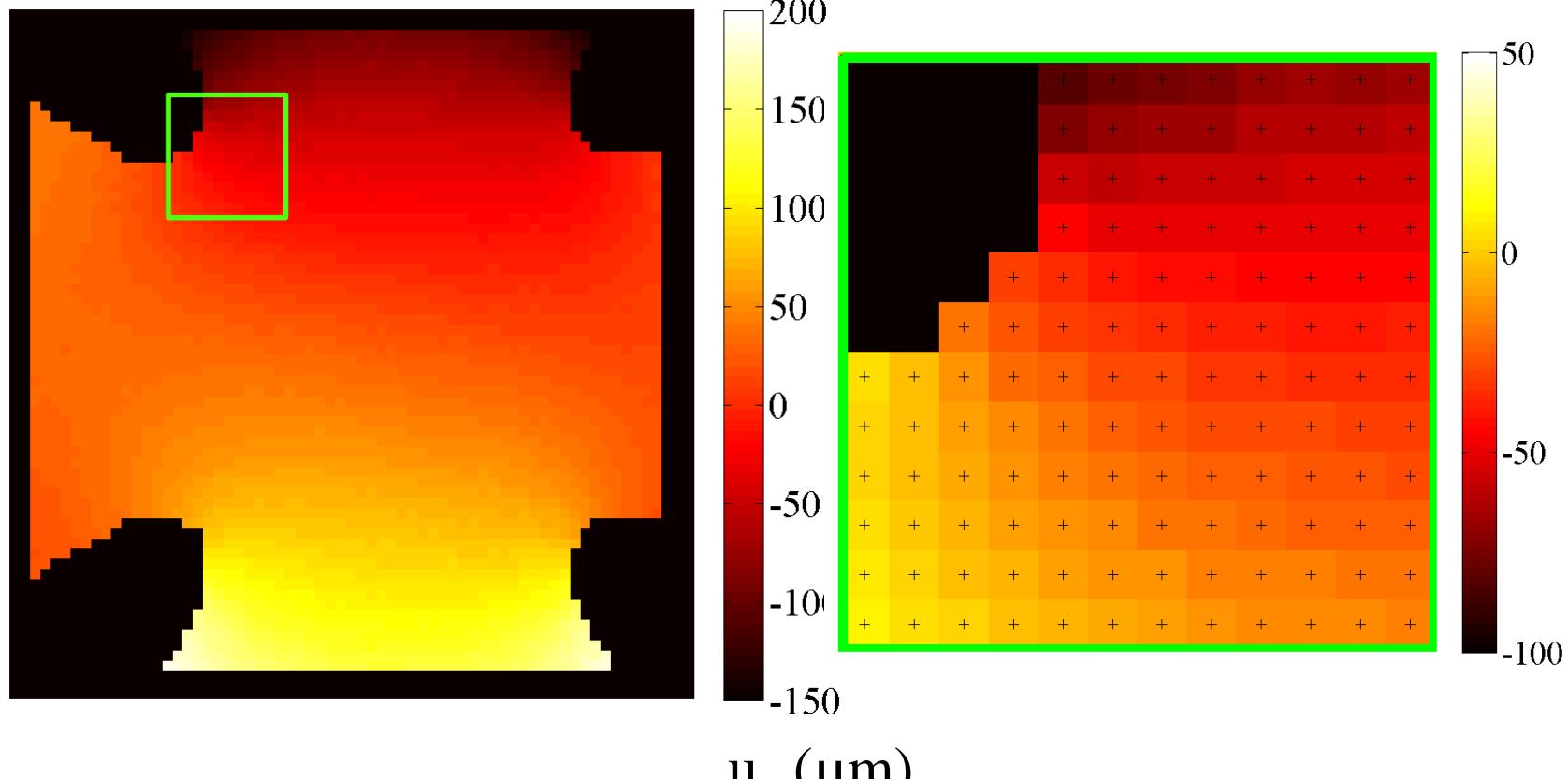
Fluid mechanics : PIV

[Barker *et al.*, 1977 ; Grousson *et al.*, 1977 ; Dudderar and Simpkins, 1977]

Solid mechanics : DIC

[Kanade *et al.*, 1981 ; Burt *et al.*, 1982 ; Sutton *et al.*, 1983]

Local Approach



→ Cloud of points

Standard Practice in Commercial Codes

GOM



GOM headquarters in Braunschweig



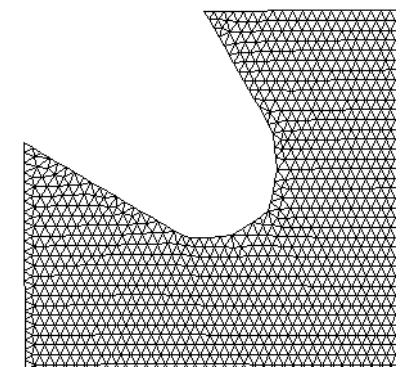
Founded in 1990

Global Approach

Measurement of optical flow

$$I_0(\mathbf{x}) \simeq I_t(\mathbf{x} + \mathbf{u}(\mathbf{x}))$$

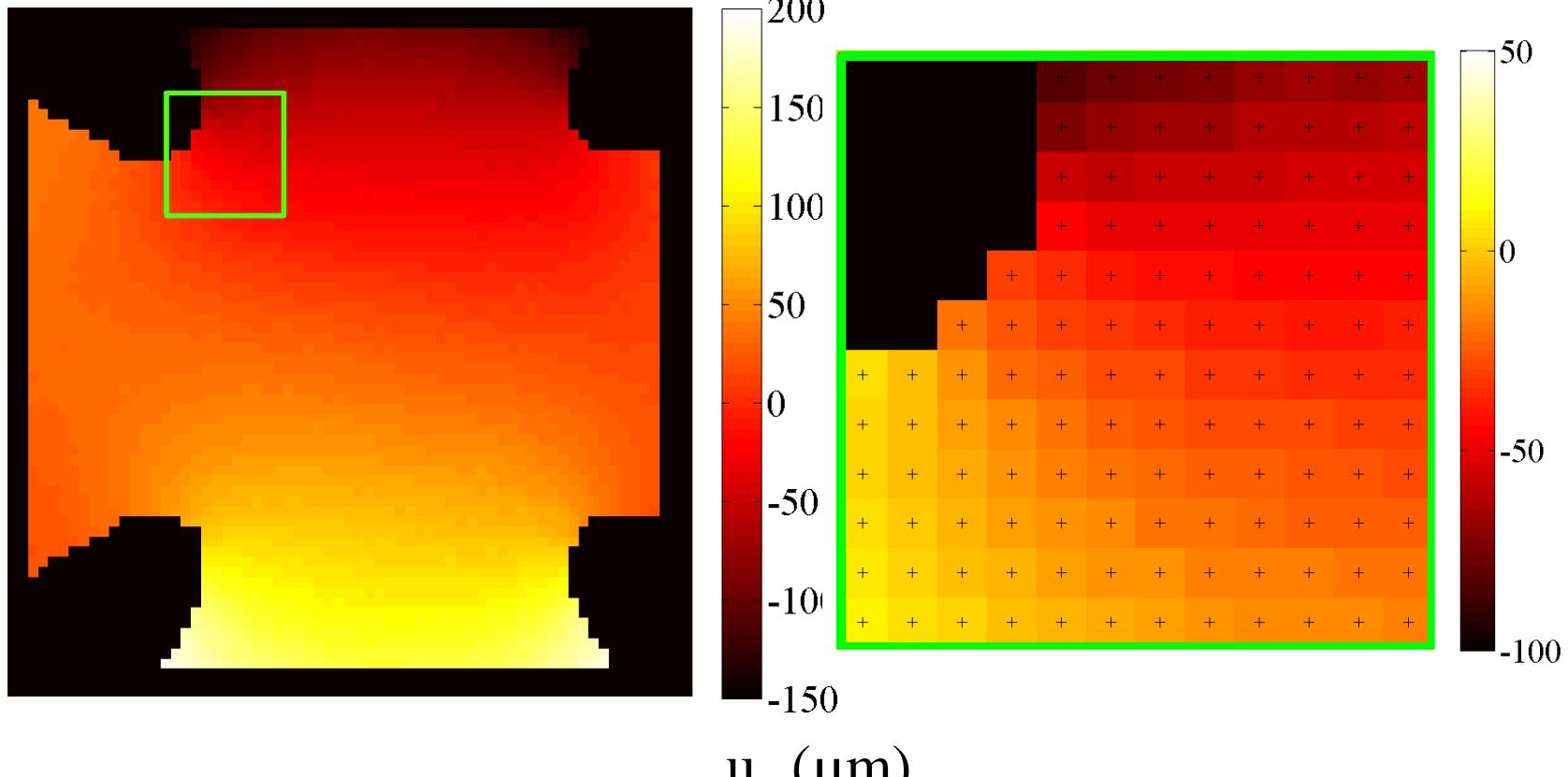
Global approach (FE bases*)



$$\mathbf{u}_m(\mathbf{x}) = \sum_i a_i \mathbf{N}_i(\mathbf{x})$$

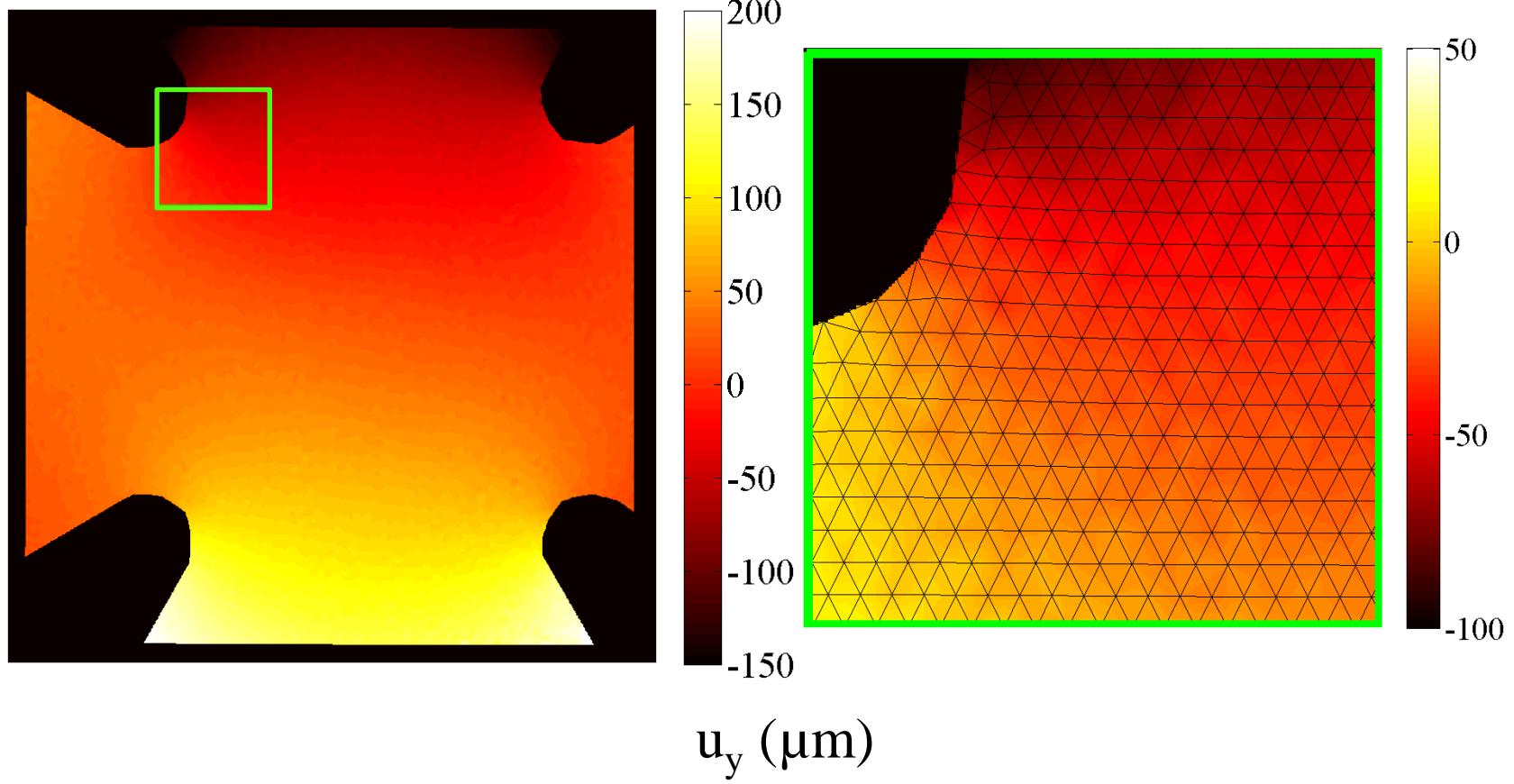
$$\eta_c^2(\{\mathbf{a}\}) = \sum_{\text{ROI}} [I_0(\mathbf{x}) - I_t(\mathbf{x} + \mathbf{u}_m(\mathbf{x}))]^2$$

Local Approach



→ Cloud of points

Global Approach



→ Dense and continuous field

Mechanical Regularization

- Gray level conservation

$$\eta_c^2(\{\mathbf{a}\}) = \sum_{\text{ROI}} [I_0(\mathbf{x}) - I_t(\mathbf{x} + \mathbf{u}_m(\mathbf{x}))]^2$$

- Internal equilibrium

$$\eta_{EQ}^2(\{\mathbf{a}\}) = \{\mathbf{a}\}^t [\mathbf{K}]^t [\mathbf{K}] \{\mathbf{a}\}$$

- Boundary regularization

$$\eta_{EP}^2(\{\mathbf{a}\}) = \{\mathbf{a}\}^t [\mathbf{L}]^t [\mathbf{L}] \{\mathbf{a}\}$$

$$\boxed{\eta_{tot}^2(\{\mathbf{a}\}) = \eta_c^2(\{\mathbf{a}\}) + w_{EQ}\eta_{EQ}^2(\{\mathbf{a}\}) + w_{EP}\eta_{EP}^2(\{\mathbf{a}\})}$$

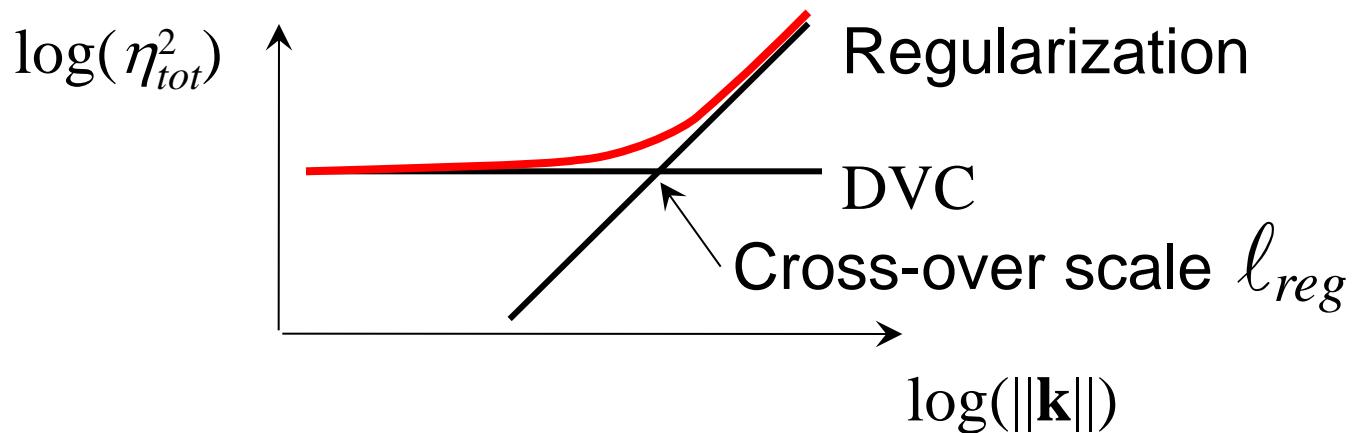
New Length Scale(s)

- Choice: plane wave for $\mathbf{v}(\mathbf{x}) = \mathbf{v}_0 e^{i\mathbf{k}\cdot\mathbf{x}}$

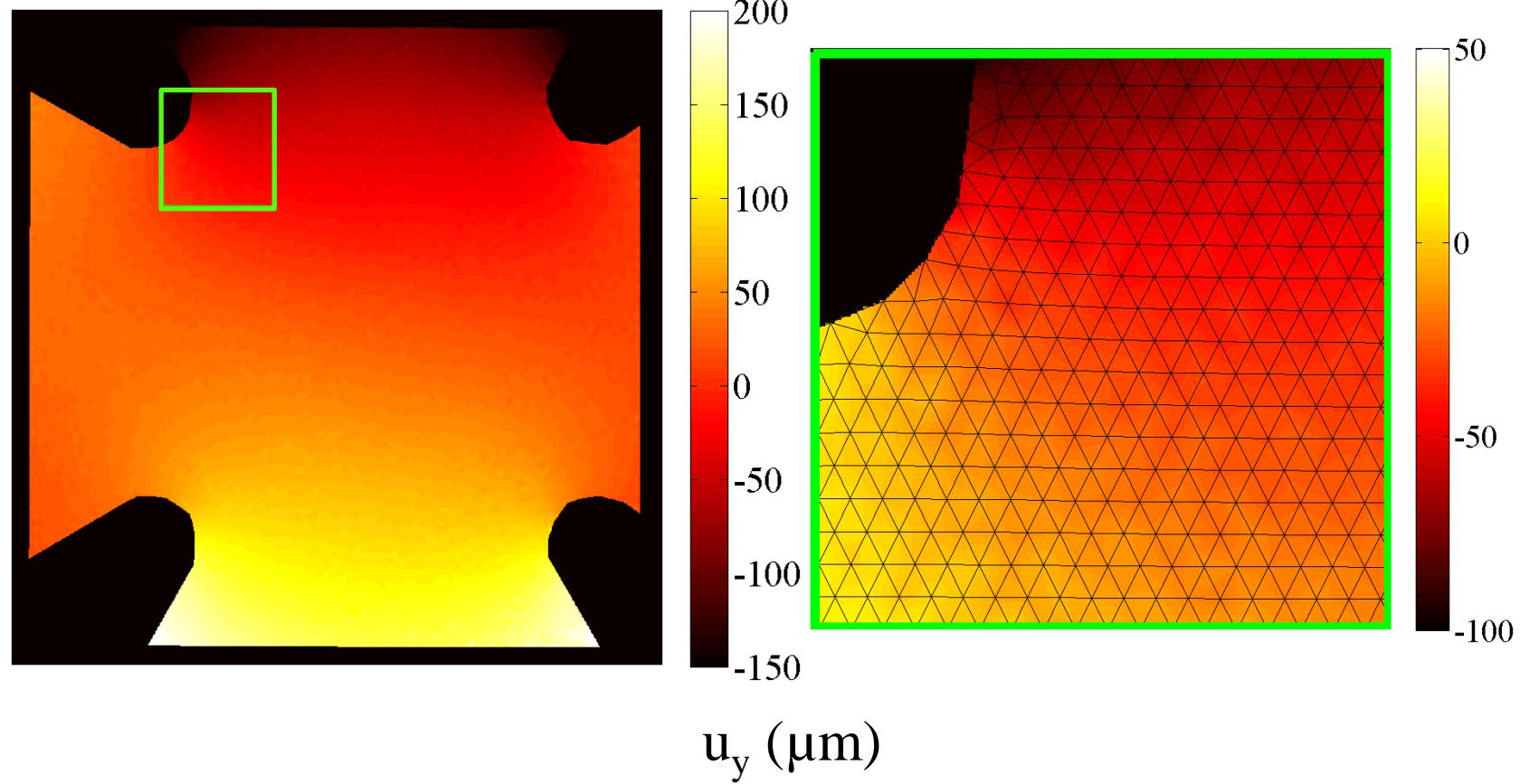
$$\eta_c^2(\mathbf{v}) \propto \|\mathbf{k}\|^0$$

$$\eta_{EG}^2(\mathbf{v}) \propto \|\mathbf{k}\|^4 \quad \text{and} \quad \eta_{EP}^2(\mathbf{v}) \propto \|\mathbf{k}\|^4$$

- Weights w_{reg} proportional to ℓ_{reg}^4

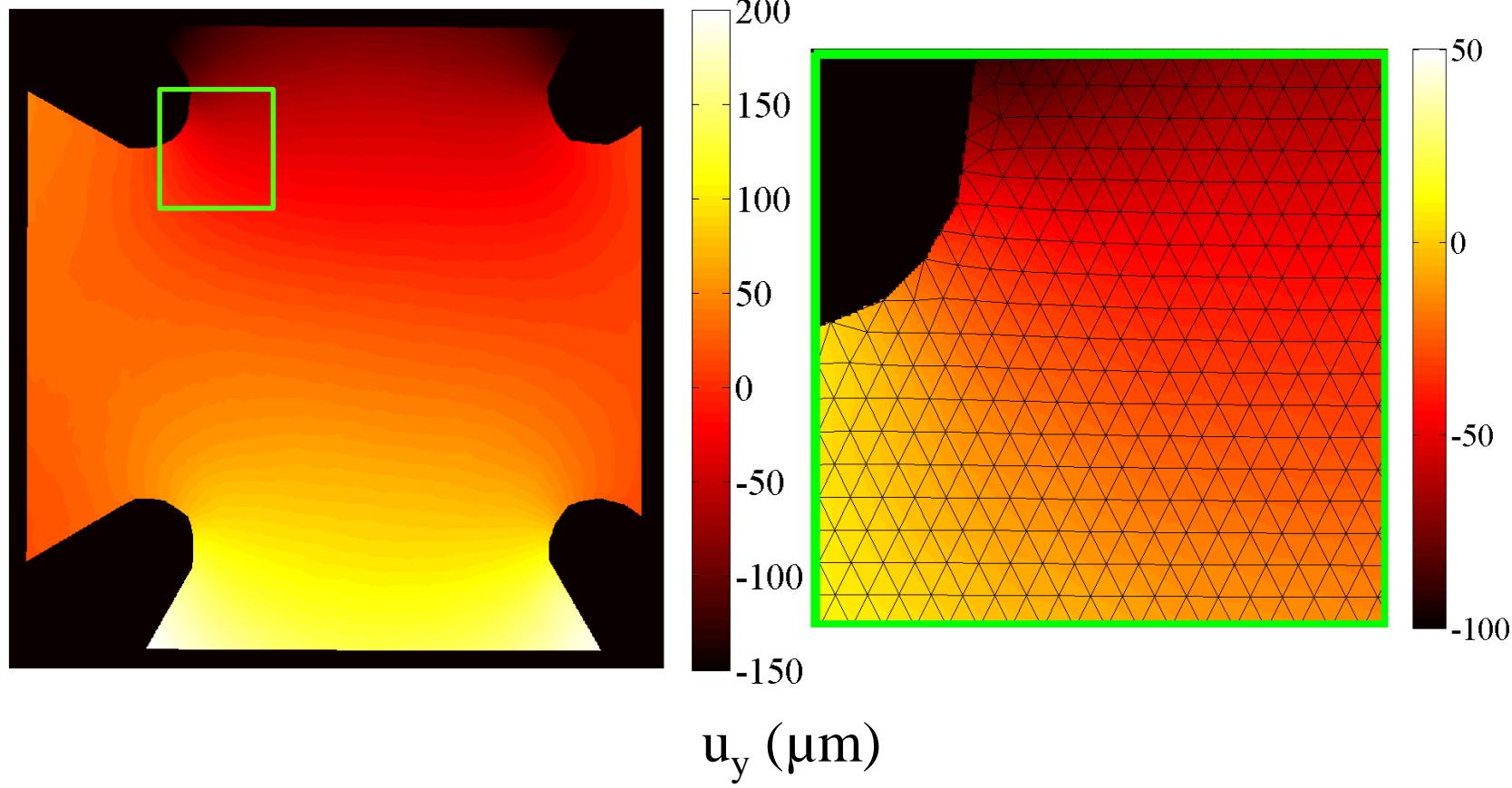


Global Approach



→ Dense and continuous field

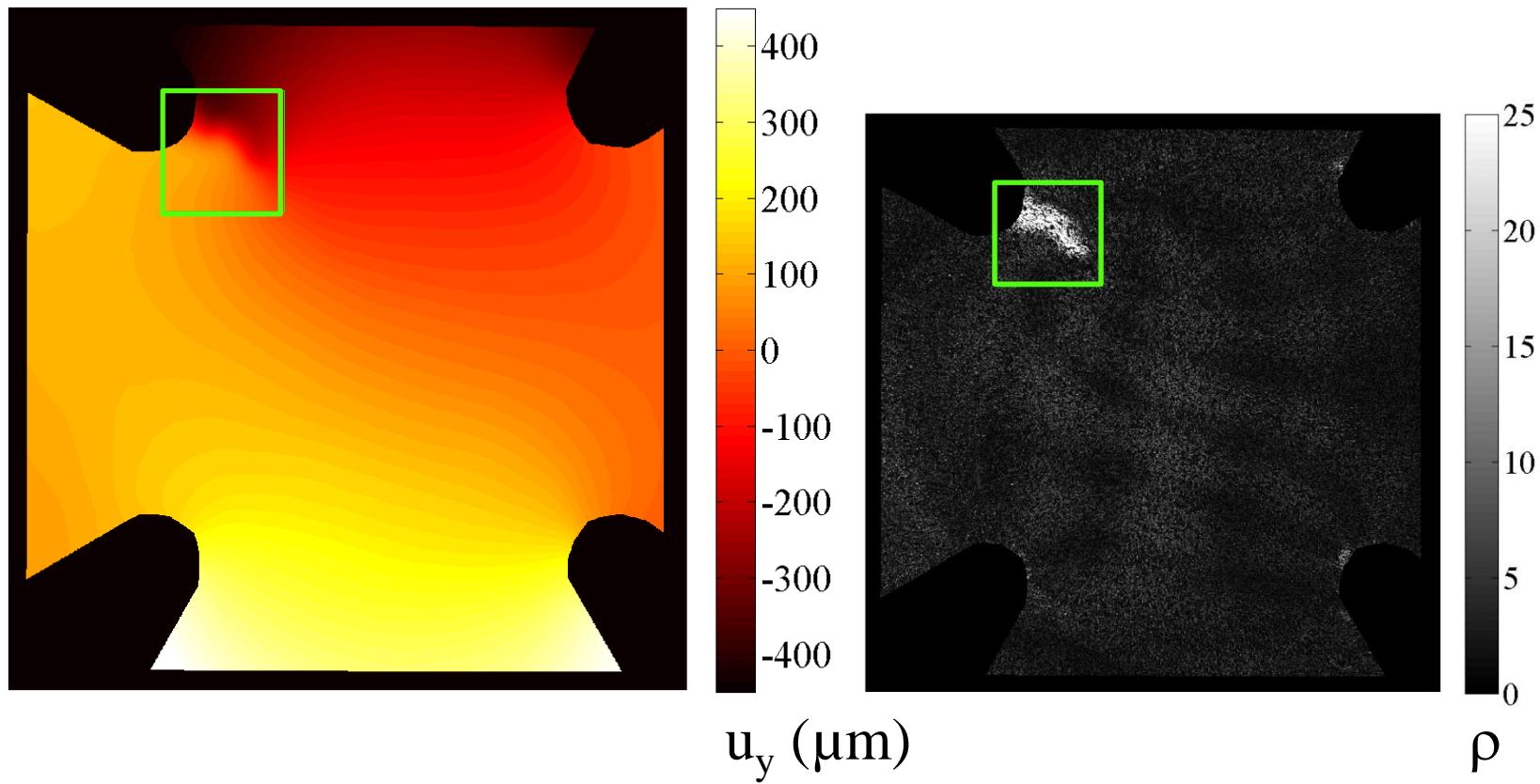
Reguralized Approach (mechanical filter)



→ Dense, continuous and filtered field

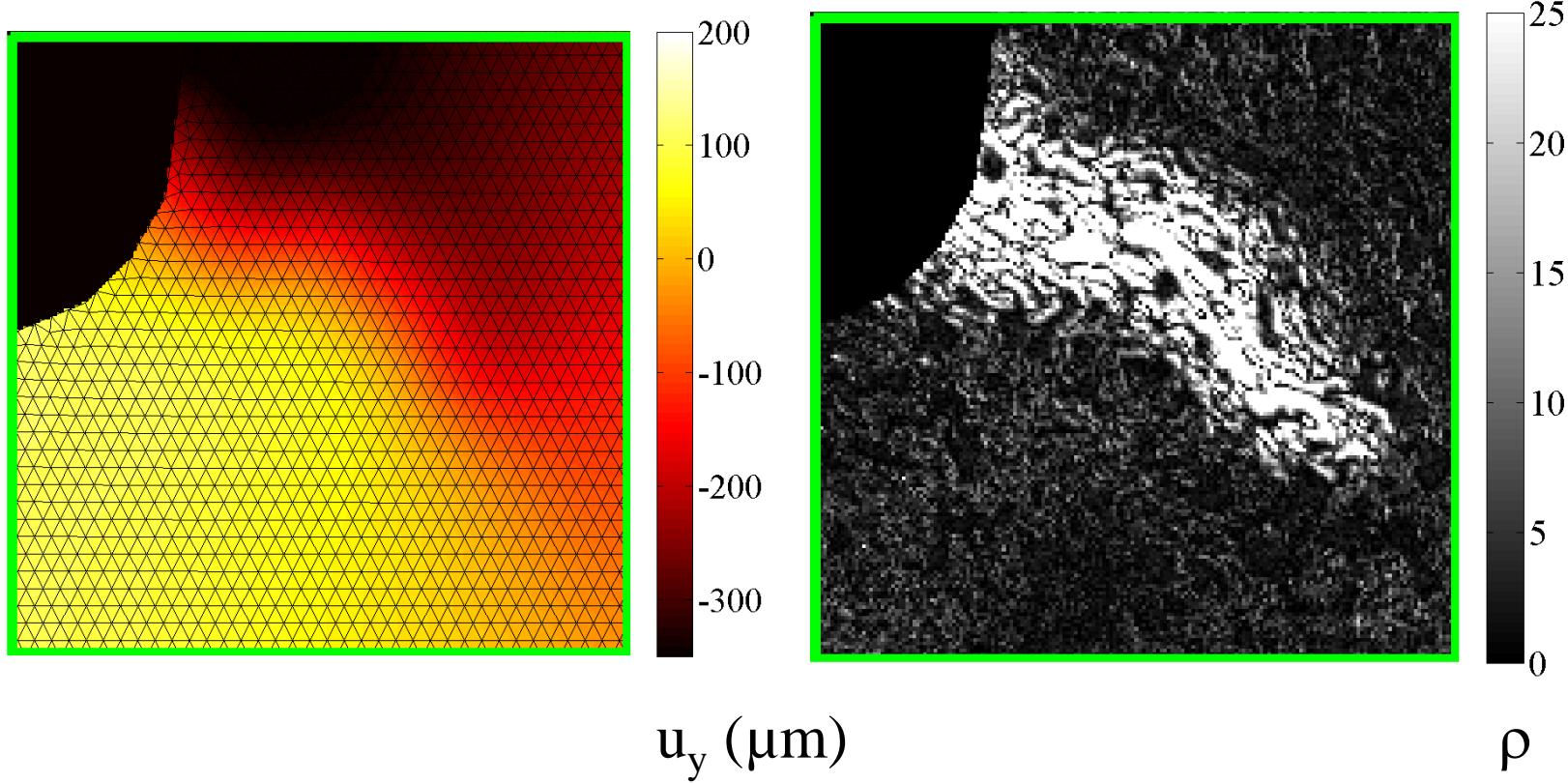
Cracks?

Reguralized Approach (w/ Crack)



$$\rho(\mathbf{x}) = |I_0(\mathbf{x}) - I_t(\mathbf{x} + \mathbf{u}_m(\mathbf{x}))|$$

Reguralized Approach (w/ Crack)



$$\rho(\mathbf{x}) = |I_0(\mathbf{x}) - I_t(\mathbf{x} + \mathbf{u}_m(\mathbf{x}))|$$

Mechanical Regularization w/ Damage

- Gray level conservation

$$\eta_c^2(\{\mathbf{a}\}) = \sum_{\text{ROI}} [I_0(\mathbf{x}) - I_t(\mathbf{x} + \mathbf{u}_m(\mathbf{x}))]^2$$

- Internal equilibrium

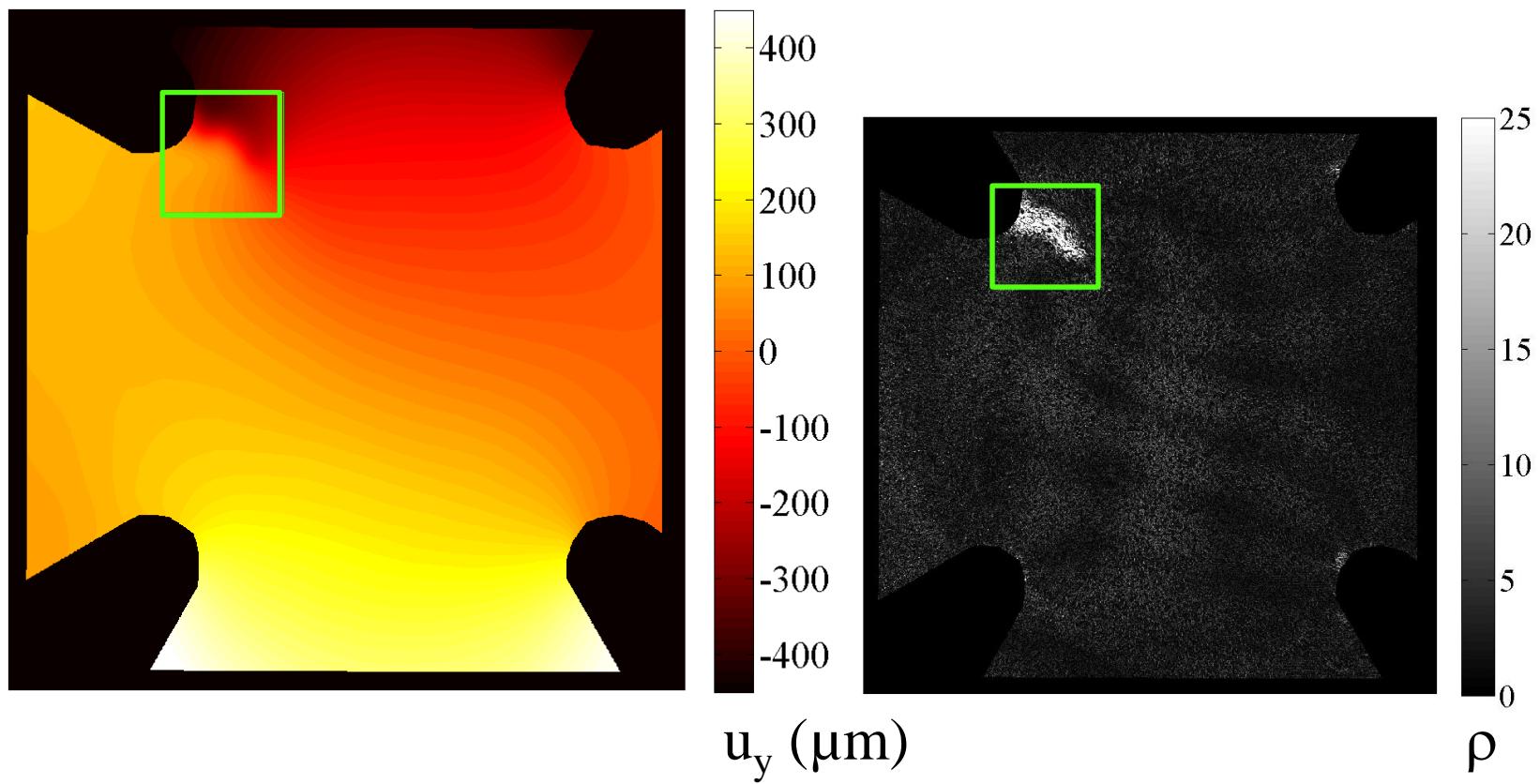
$$\eta_{EQ}^2(\{\mathbf{a}\}) = \{\mathbf{a}\}^t [\tilde{\mathbf{K}}]^t [\tilde{\mathbf{K}}] \{\mathbf{a}\}$$

- with

$$[\tilde{\mathbf{K}}^e] = [\mathbf{K}^e](1 - D^e) \quad D^e = D_\infty \left(1 - \exp \left(- \frac{\langle \varepsilon_1^e \rangle}{\varepsilon_0} \right)^m \right)$$

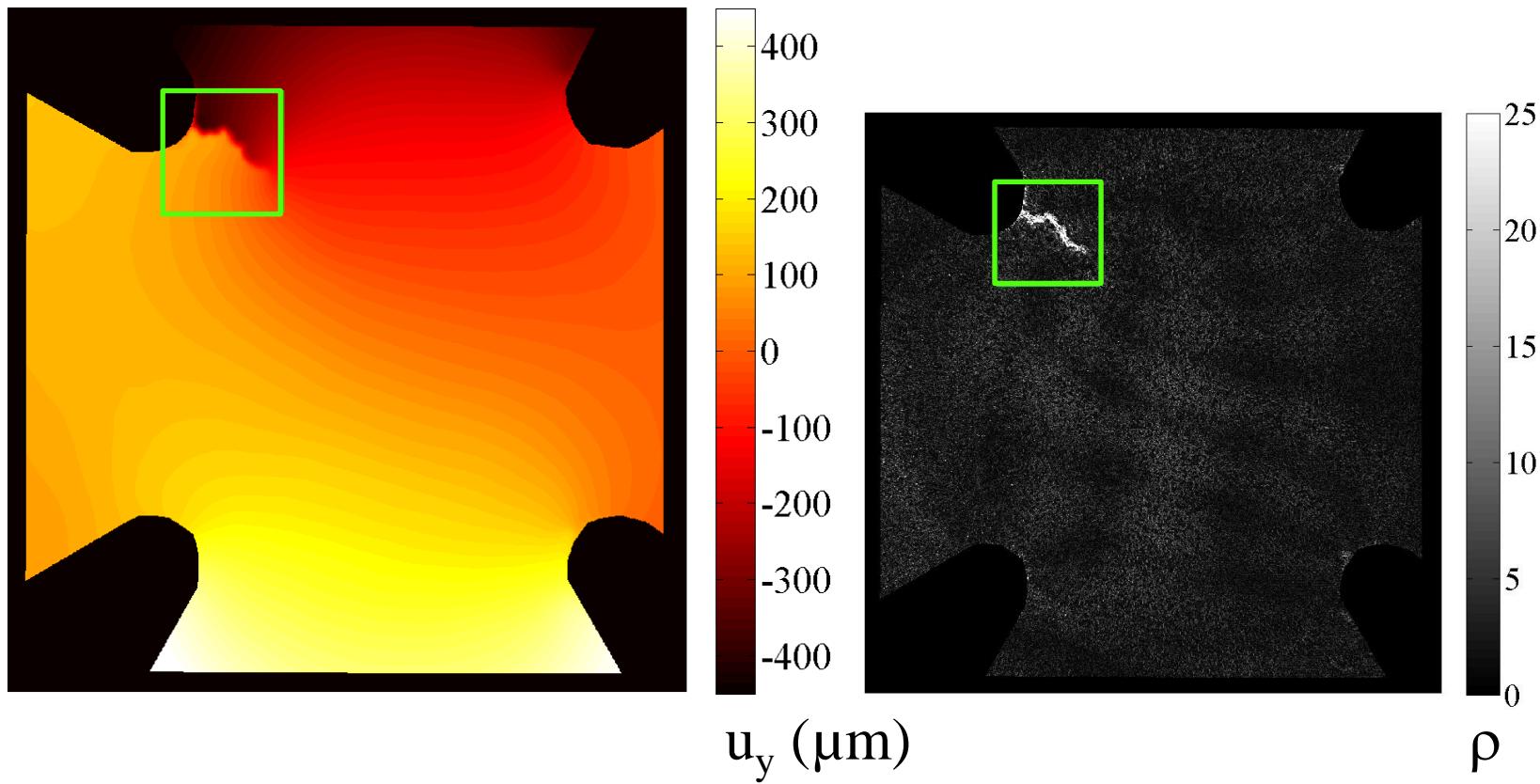
$$\boxed{\eta_{tot}^2(\{\mathbf{a}\}) = \eta_c^2(\{\mathbf{a}\}) + w_{EQ} \eta_{EQ}^2(\{\mathbf{a}\}) + w_{EP} \eta_{EP}^2(\{\mathbf{a}\})}$$

Reguralized Approach (w/ Crack)

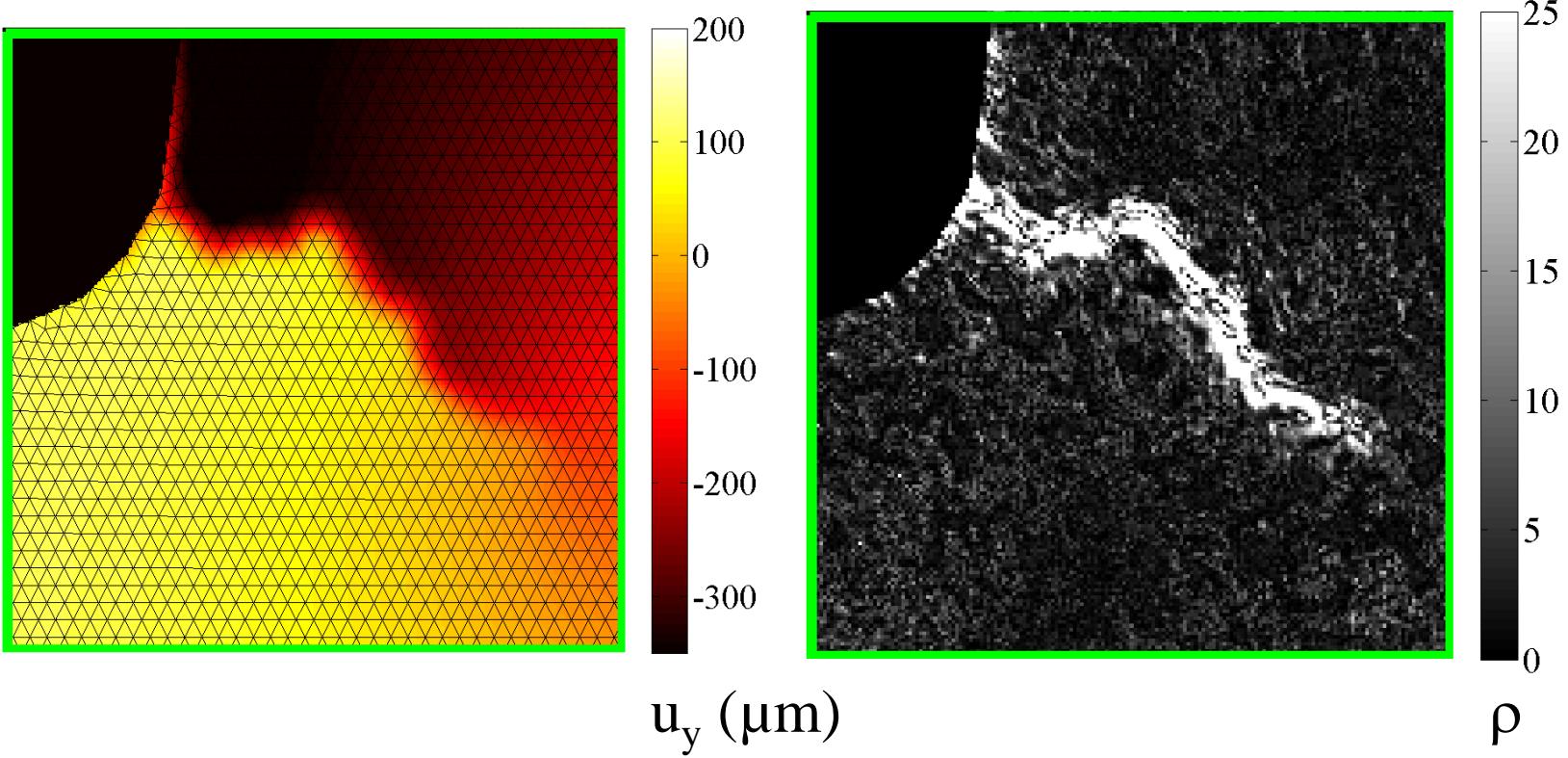




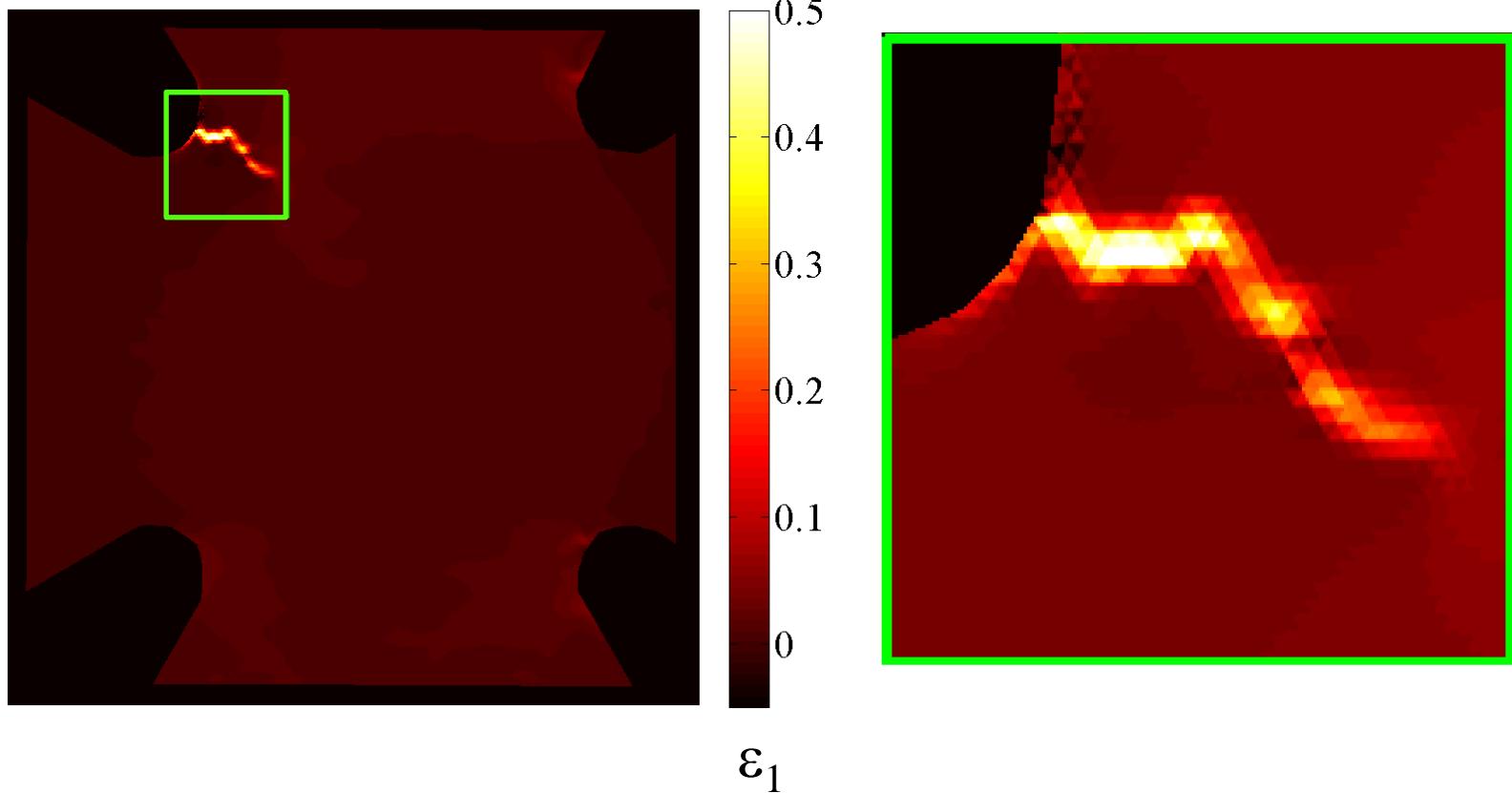
Reguralized Approach w/ Damage



Reguralized Approach w/ Damage



Reguralized Approach w/ Damage



Cracks in 3D?

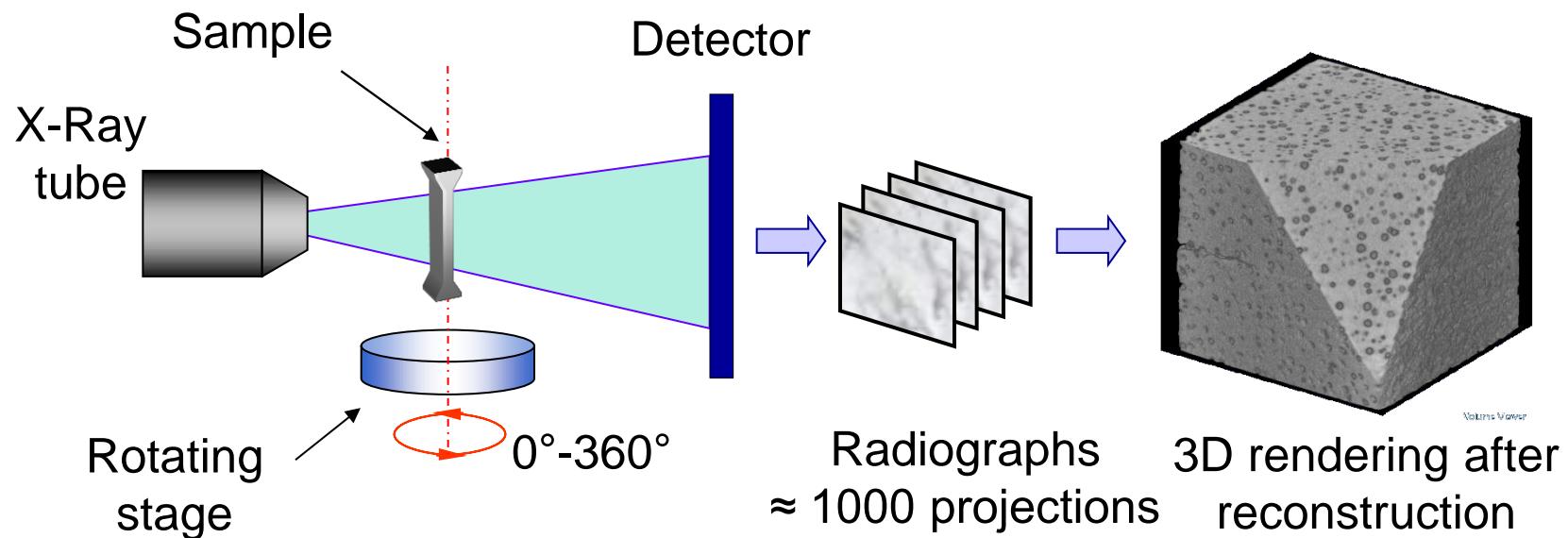
X-Ray Imaging



Lab tomograph

3rd generation synchrotron facilities

X-Ray Computed Tomography



Digital **Volume** Correlation

Local approach*

$$(I_0 * I_t)(\mathbf{u}) = \sum_{\text{ZOI}} I_0(\mathbf{x}) I_t(\mathbf{x} + \mathbf{u})$$

Global approach**

$$\eta_c^2(\{\mathbf{a}\}) = \sum_{\text{ROI}} [I_0(\mathbf{x}) - I_t(\mathbf{x} + \mathbf{u}_m(\mathbf{x}))]^2$$

Regularized approach***

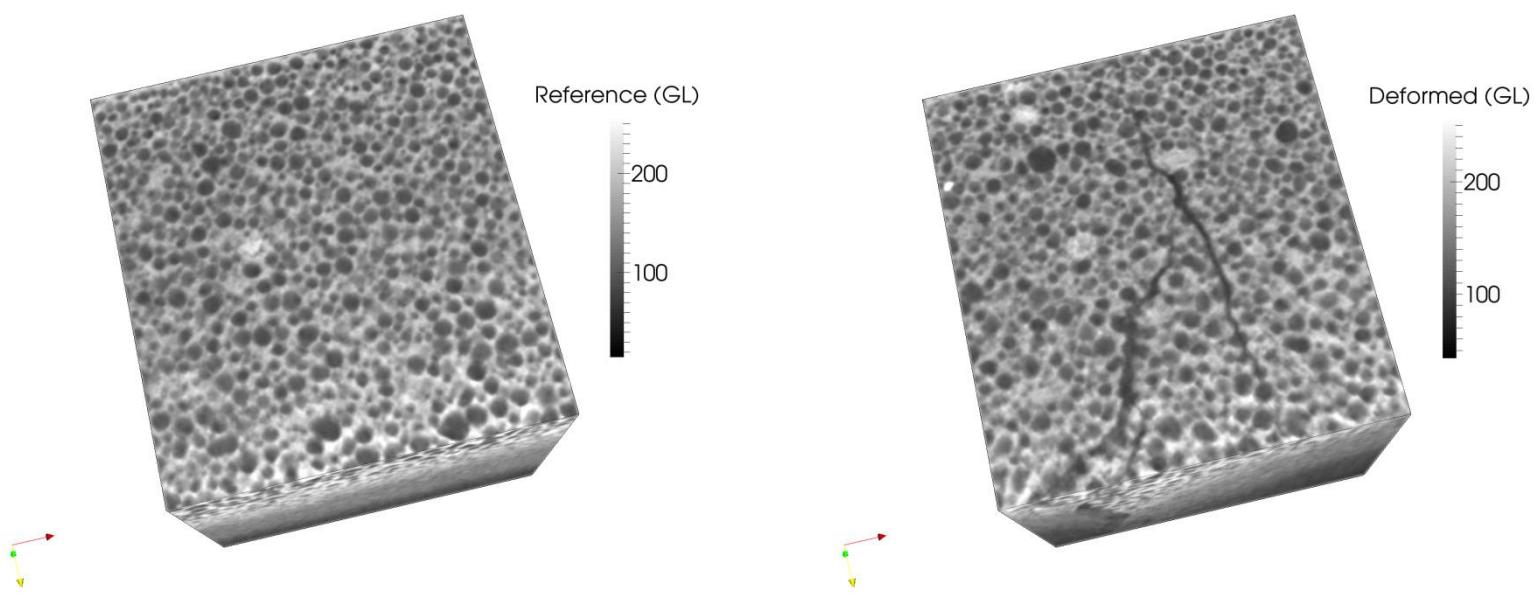
$$\eta_{tot}^2(\{\mathbf{a}\}) = \eta_c^2(\{\mathbf{a}\}) + w_{EQ} \eta_{EQ}^2(\{\mathbf{a}\}) + w_{EP} \eta_{EP}^2(\{\mathbf{a}\})$$

*[Bay *et al.*, 1999, *Exp. Mech.* 39(3) pp. 217-226]

**[Roux *et al.*, 2008 *Compos. Part A* 39(8) 1253-1265]

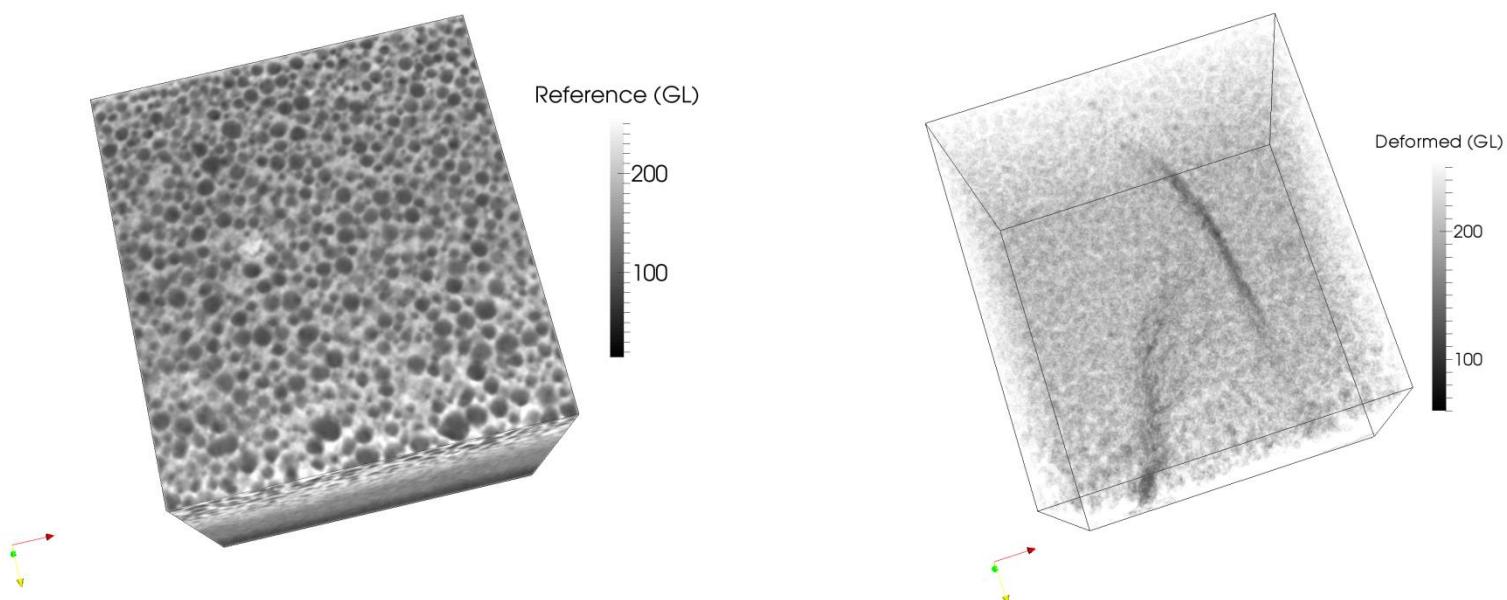
***[Leclerc *et al.*, 2011, *Exp. Mech.* 51(4) pp. 479-490]

3-Point Flexural Test on Plaster



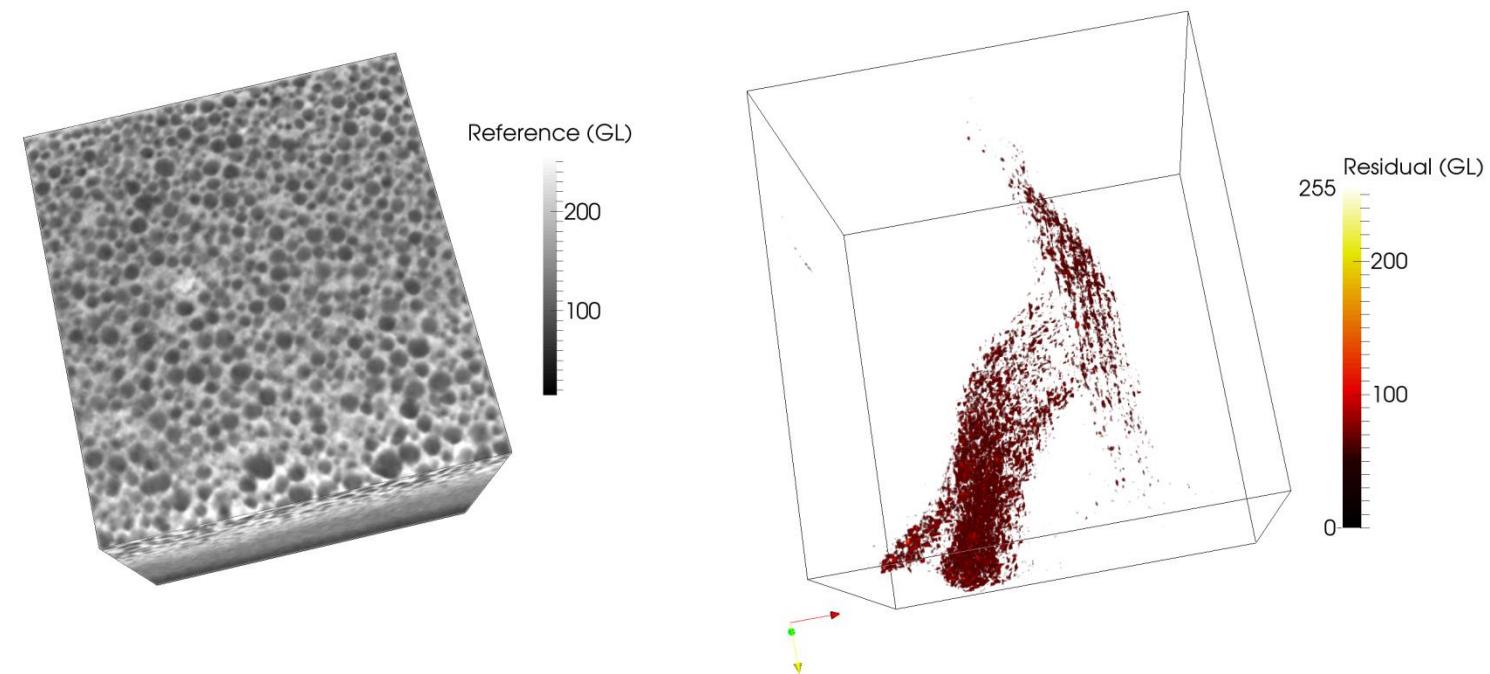
1 voxel \leftrightarrow 25 μm

3-Point Flexural Test on Plaster



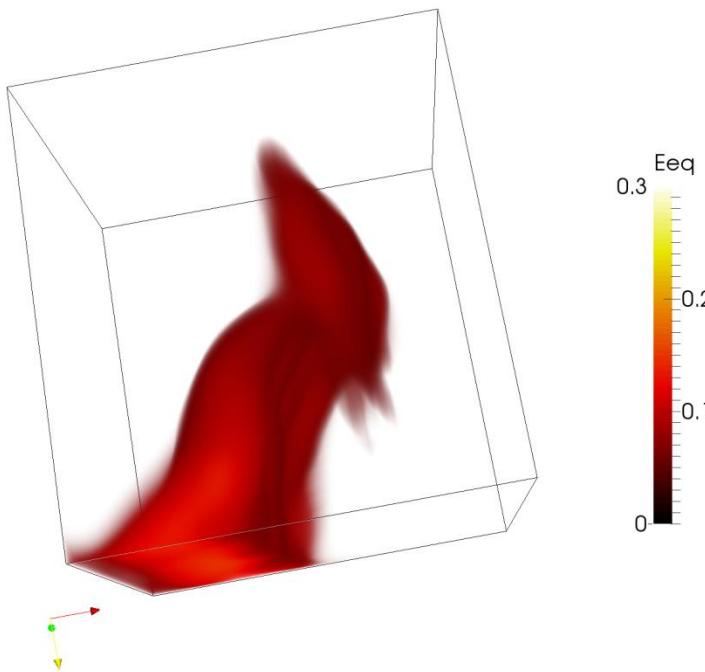
Crack visualization?

3-Point Flexural Test on Plaster



**Maximum
principal strains?
Elastic strains ?**

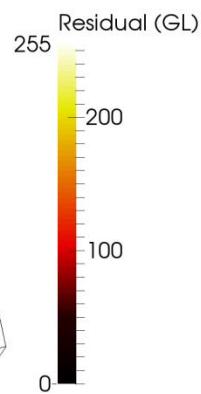
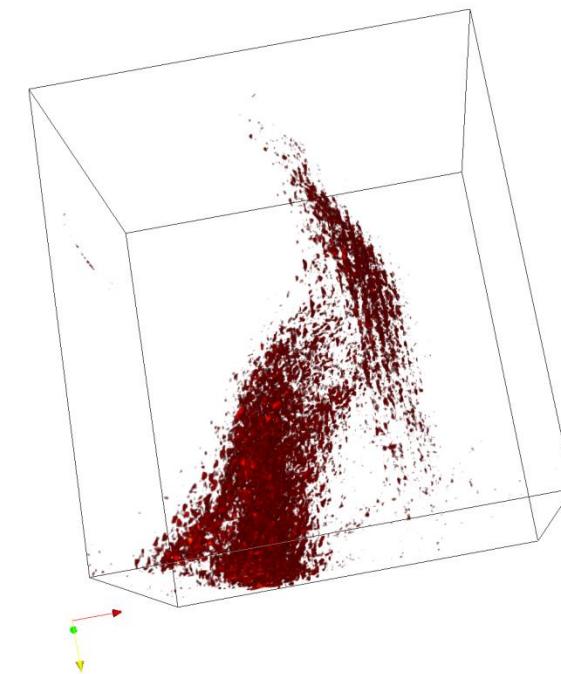
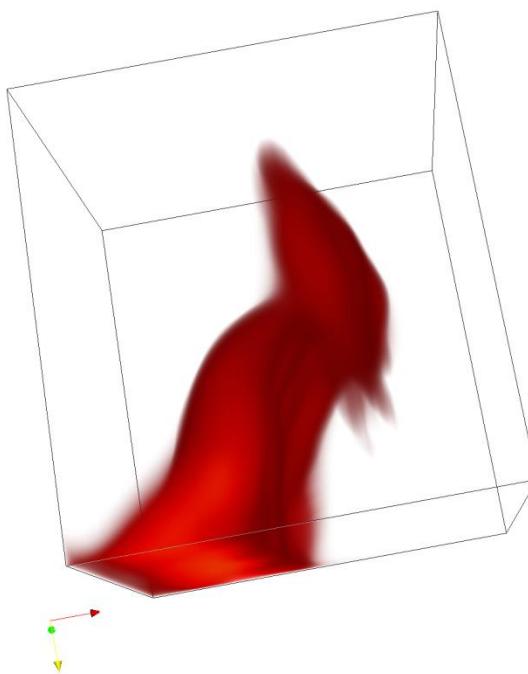
Quantified Cracking



$\ell = 8$ voxels

$\ell_m = \ell_b = 60$ voxels

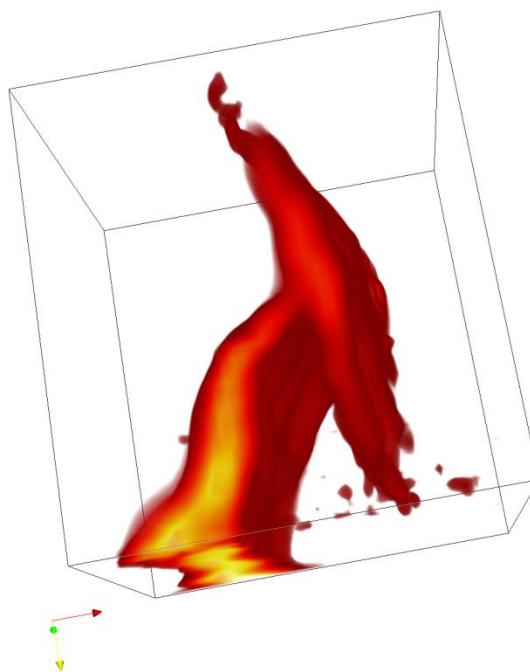
Quantified Cracking



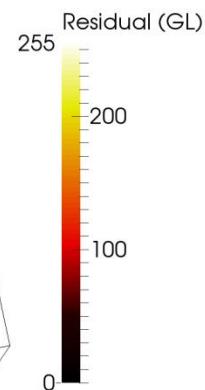
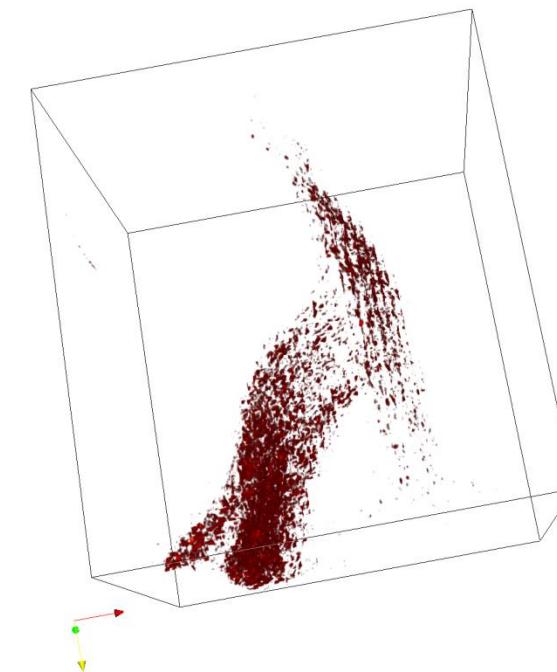
$\ell = 8$ voxels

$\ell_m = \ell_b = 60$ voxels

Quantified Cracking

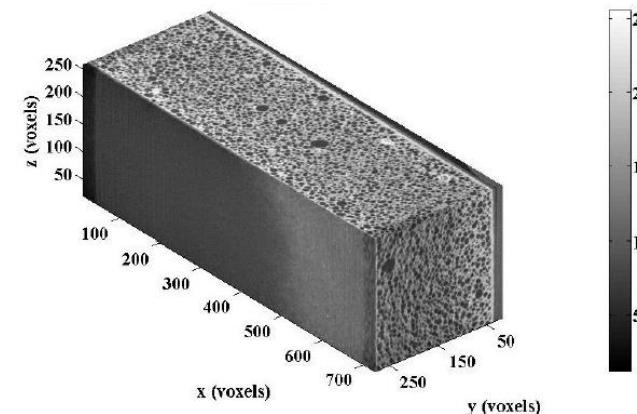


$\ell = 8$ voxels
 $\ell_m = 4\ell_b = 60$ voxels

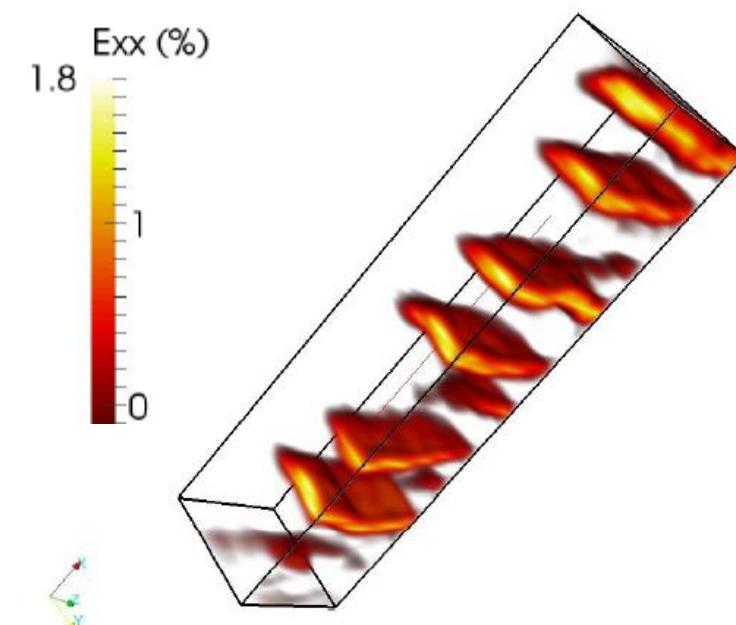


w/ damage

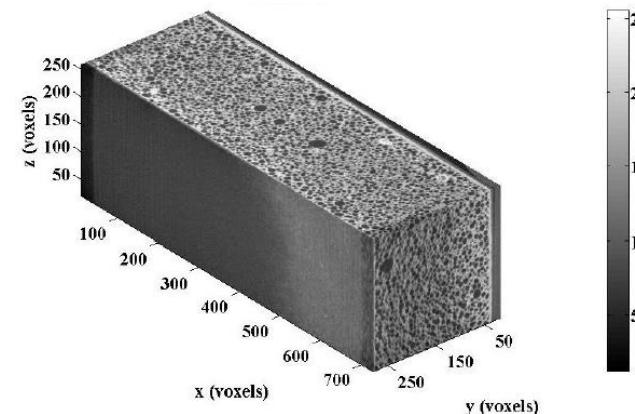
Multiple Cracking?



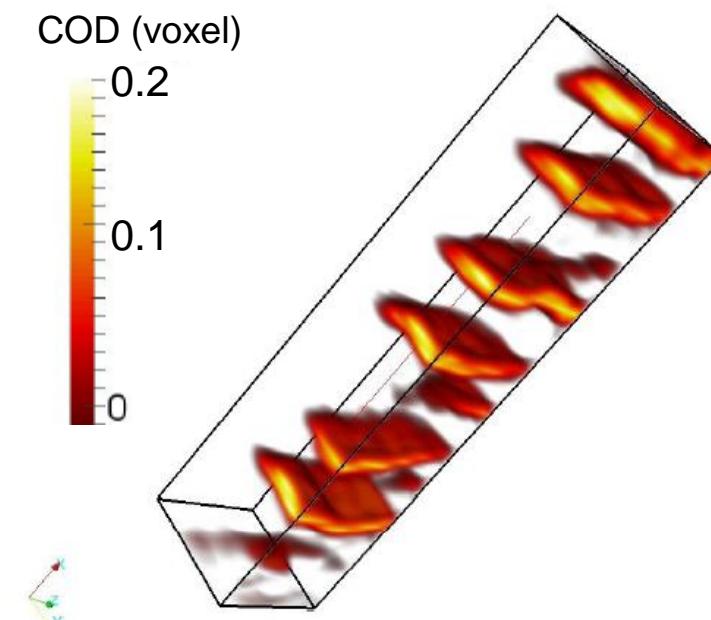
1 voxel \leftrightarrow 50 μm
 $\ell = 12$ voxels
 $\ell_m = \ell_b = 30$ voxels



Multiple Cracking



$1 \text{ voxel} \leftrightarrow 50 \mu\text{m}$
 $\ell = 12 \text{ voxels}$
 $\ell_m = \ell_b = 30 \text{ voxels}$

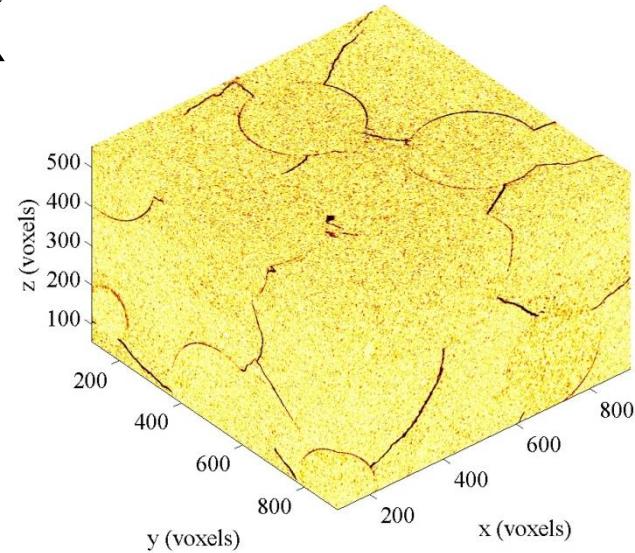


Interim Summary

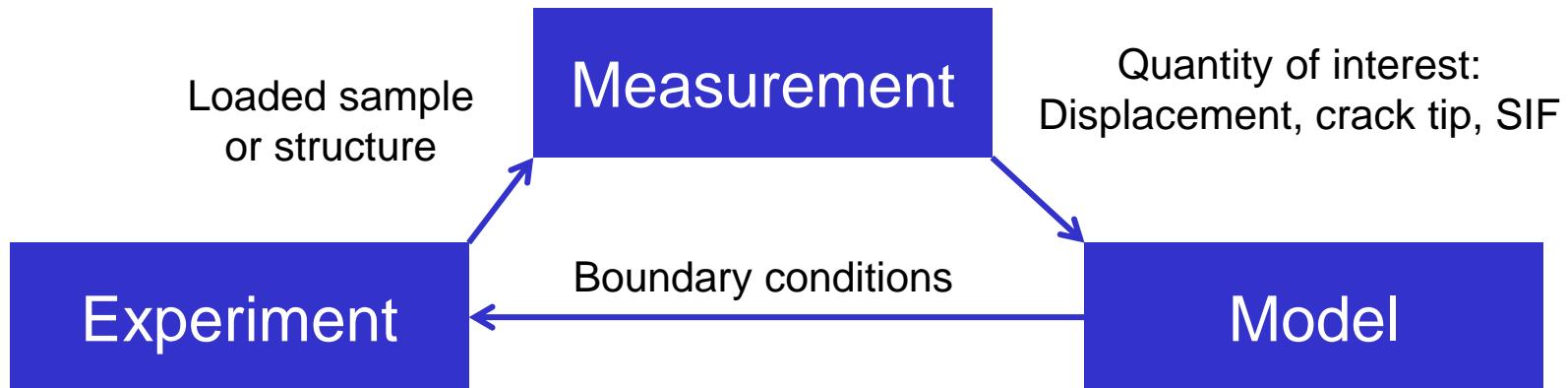
- 2D & 3D imaging:
very powerful (qualitative) tool!
- DIC and DVC:
quantitative tools
- Damage quantification in
brittle materials

Outlook

- 3D imaging:
 - big data
 - 4D extensions
- DVC:
 - big and fast calculations
 - multiscale analyses
 - robust when localization or damage set in
- Quantitative assessments of damage
- Model identification and validation

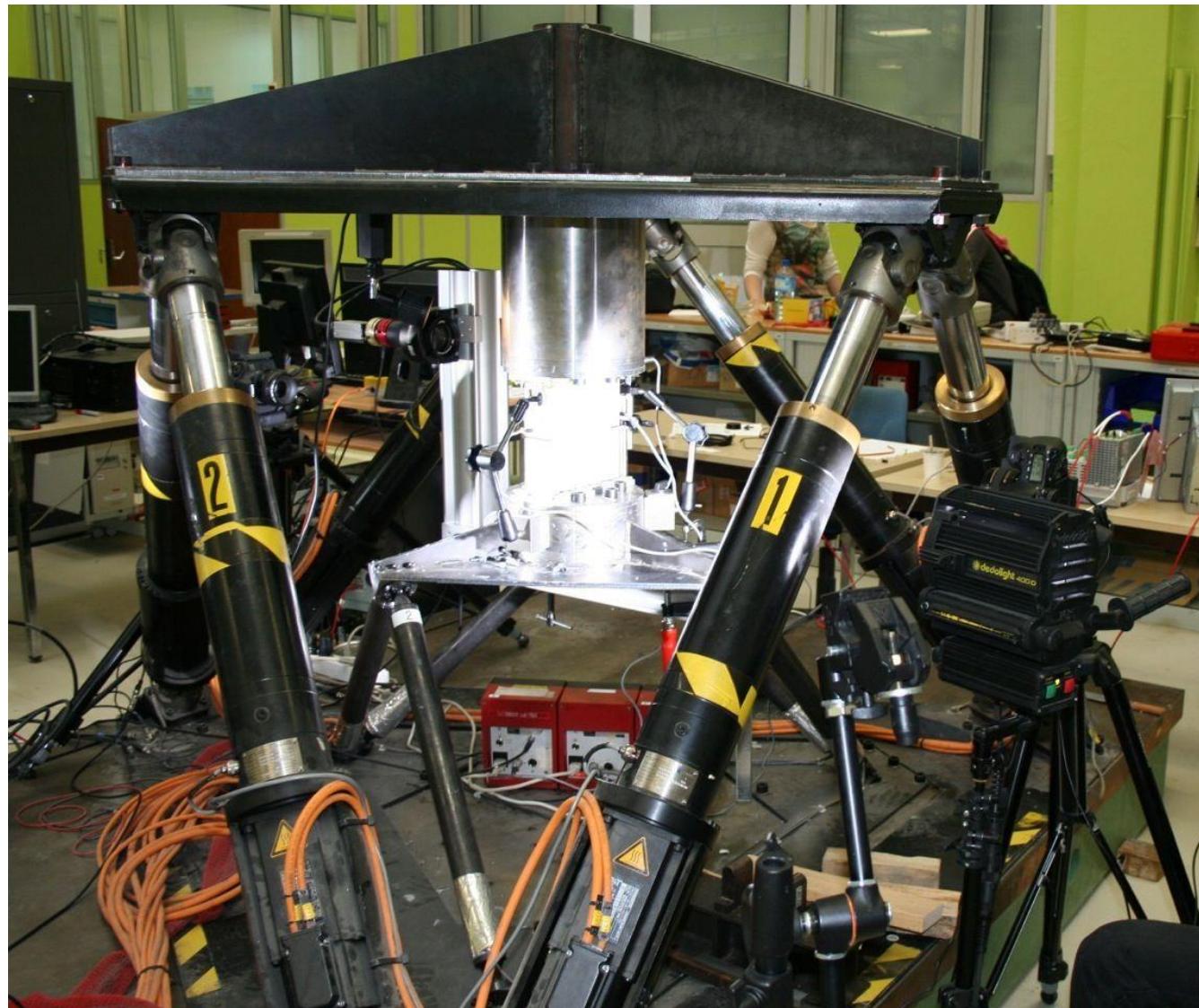


‘Smart Testing’ with DIC

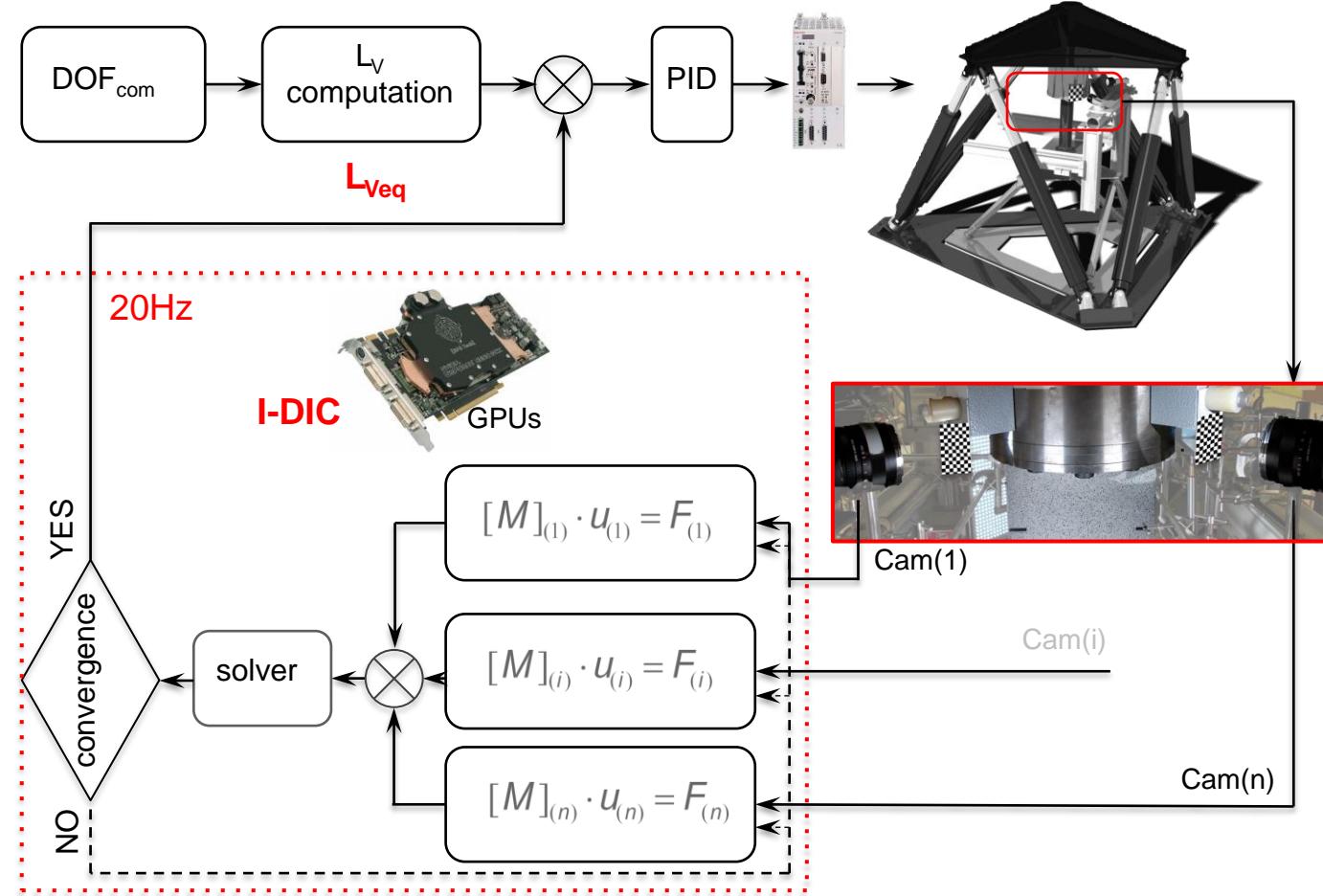


- Hexapod kinematics
- Crack path:
 - manual control (interactive procedure)
 - real time (hybrid procedure)

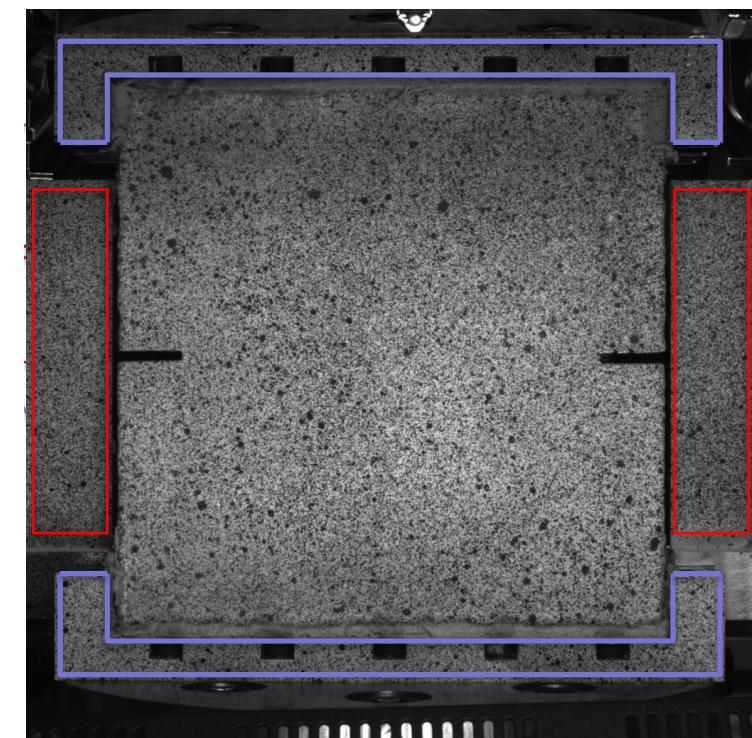
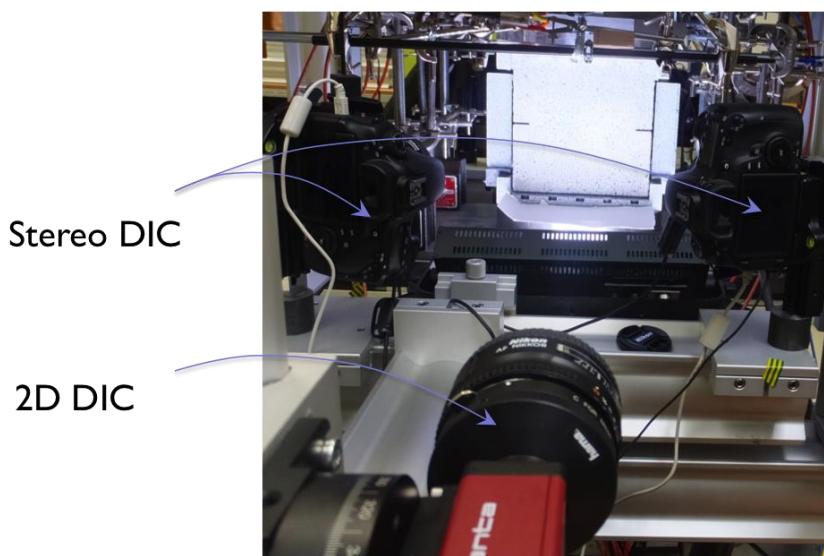
Hexapod



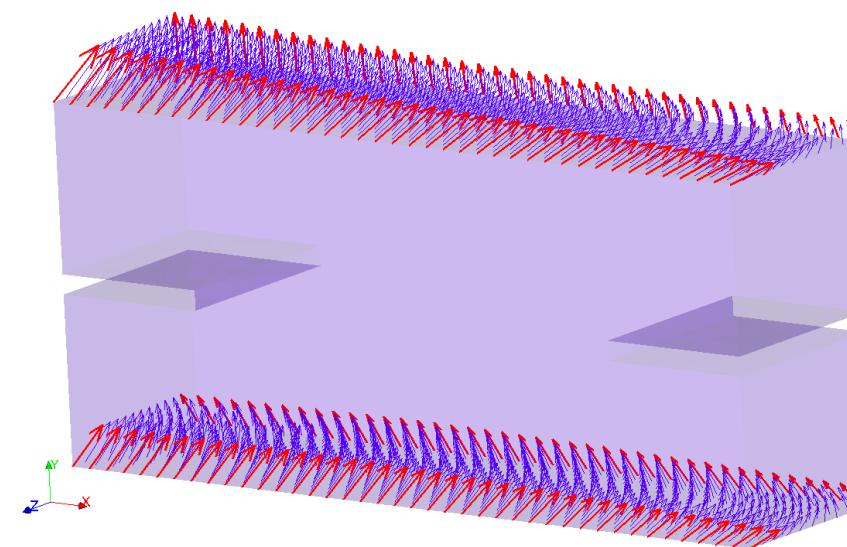
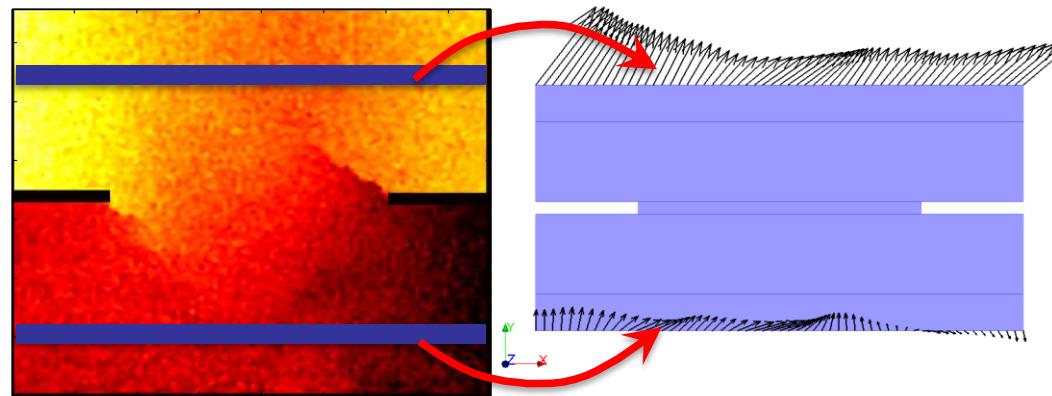
DIC-Controlled Hexapod



DIC All Over The Place...

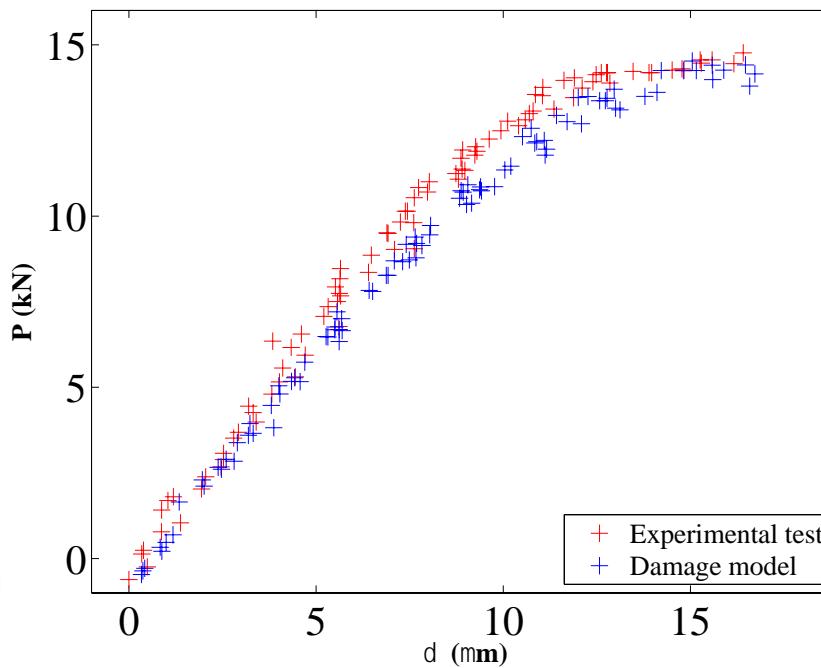


3D Simulations Driven by Measured BCs

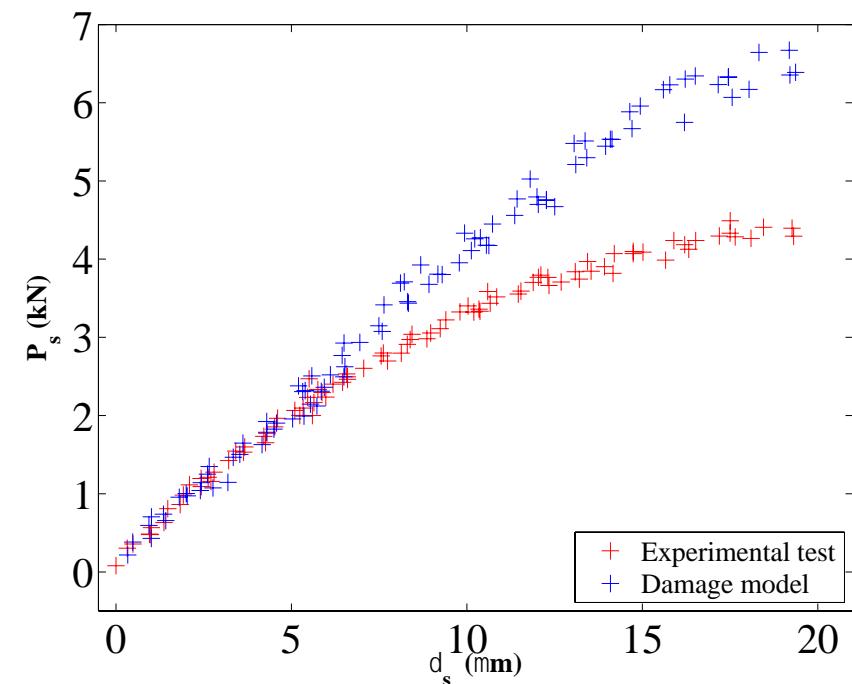


Macroscopic Validation?

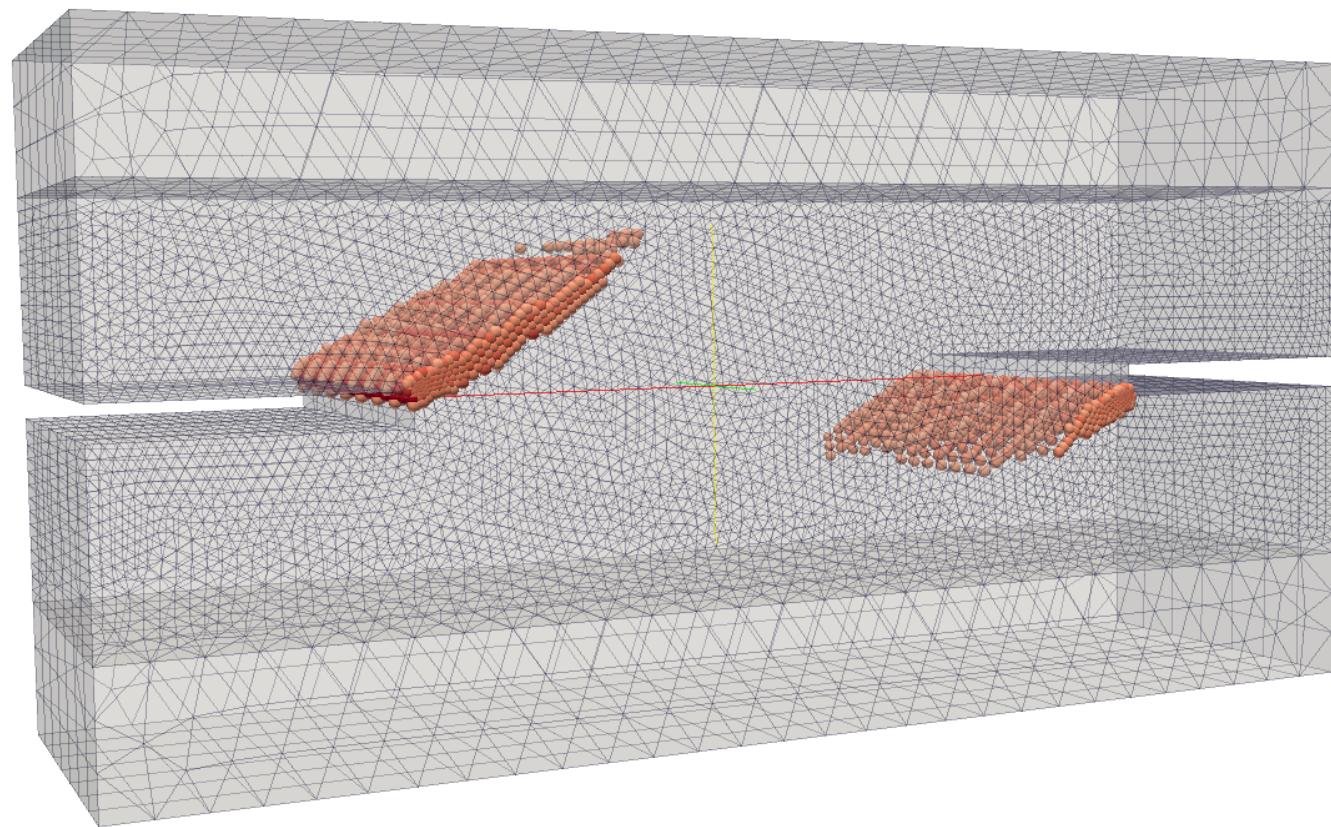
Longitudinal Response



Transverse Response

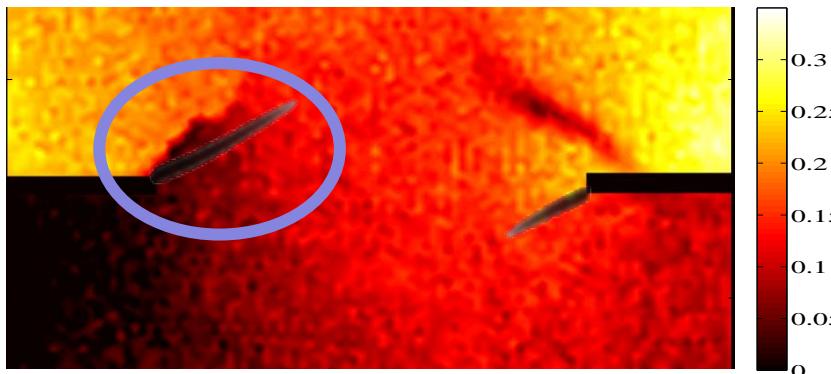


Nonlocal Damage Model

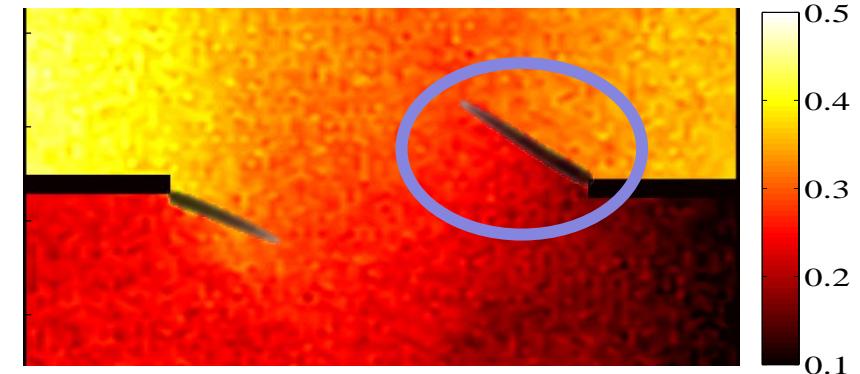


Cracking Pattern

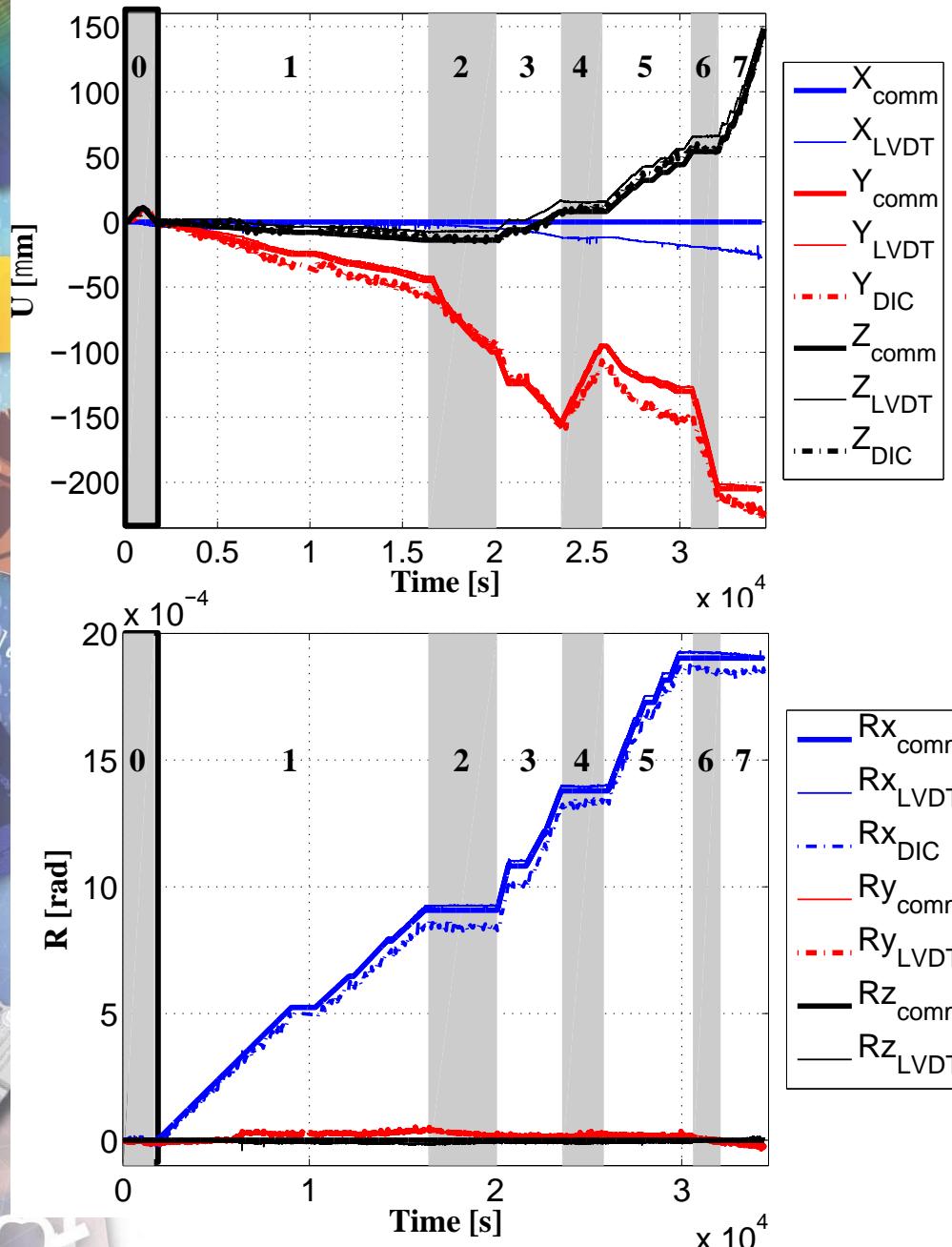
Back Face



Front Face

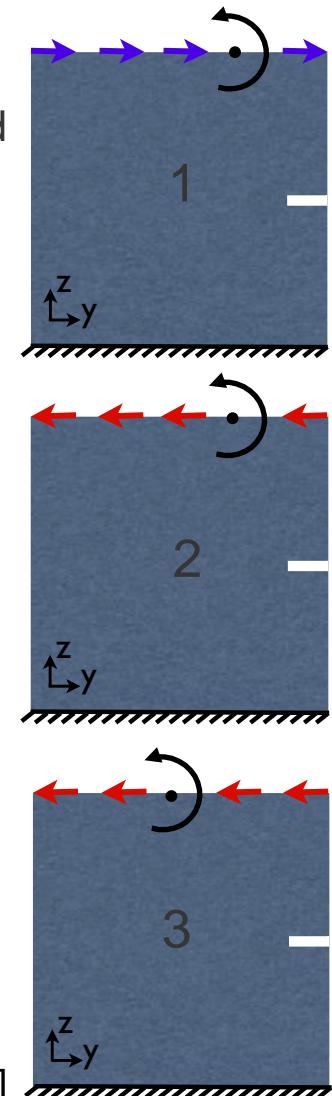


Interactive Test

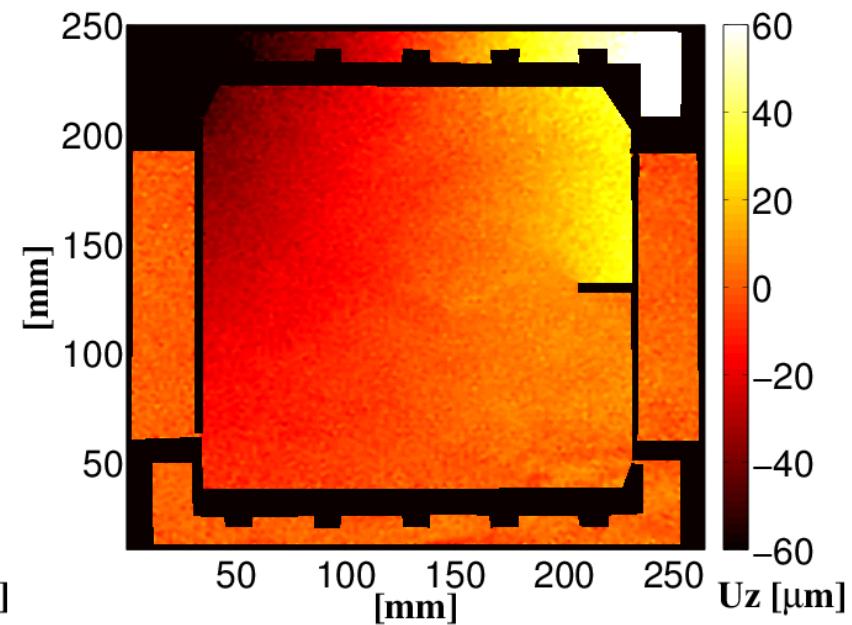
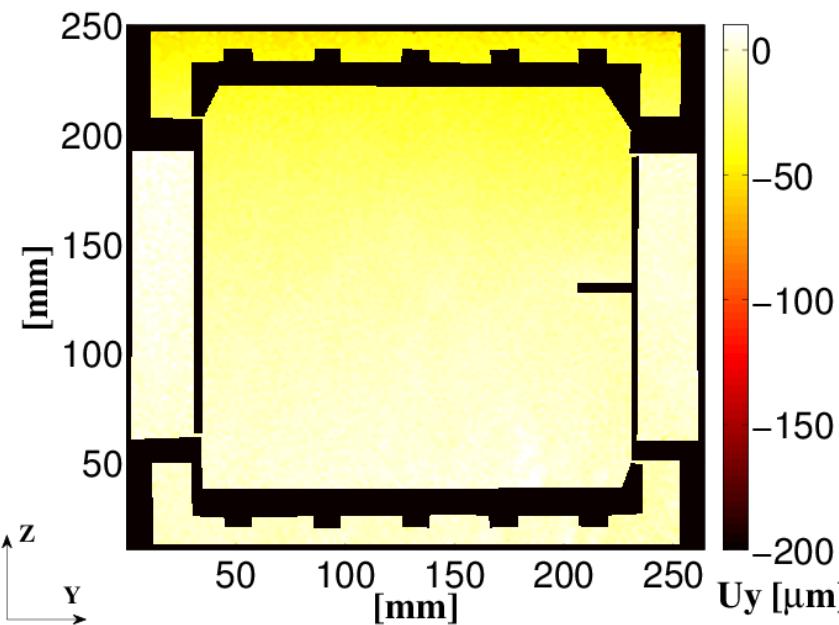
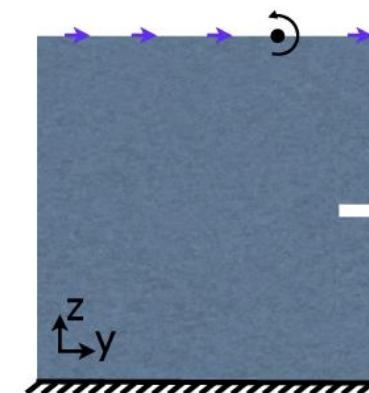
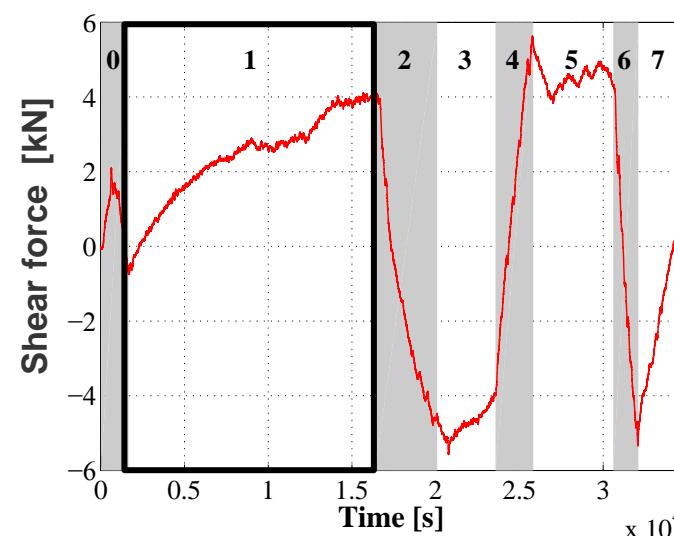


Loading steps:

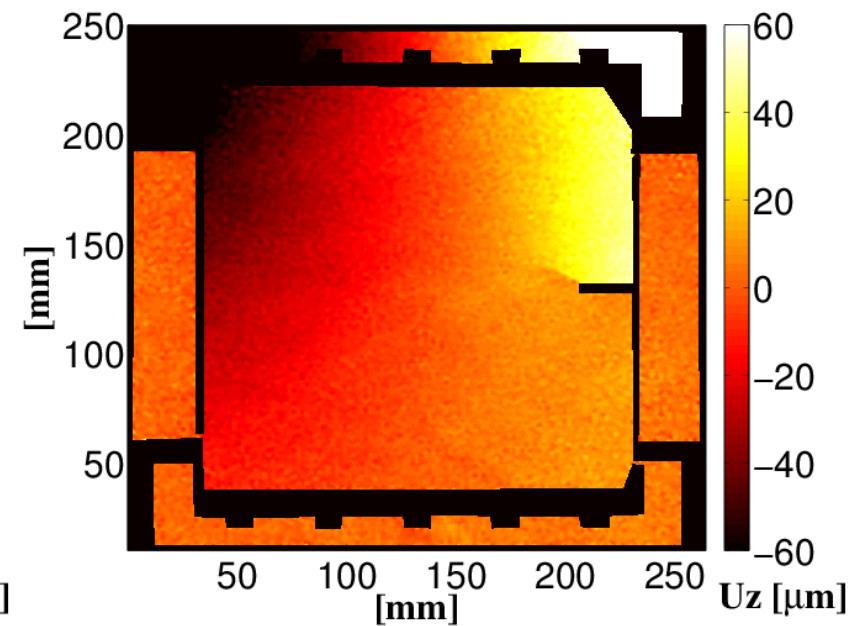
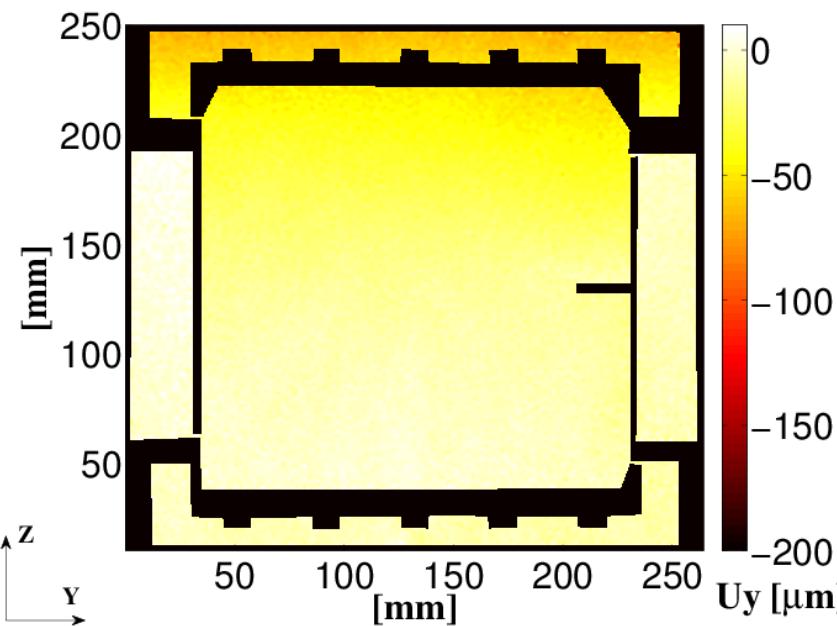
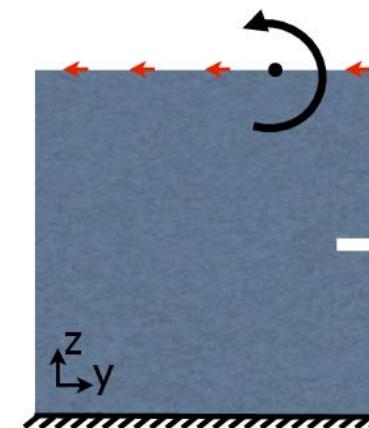
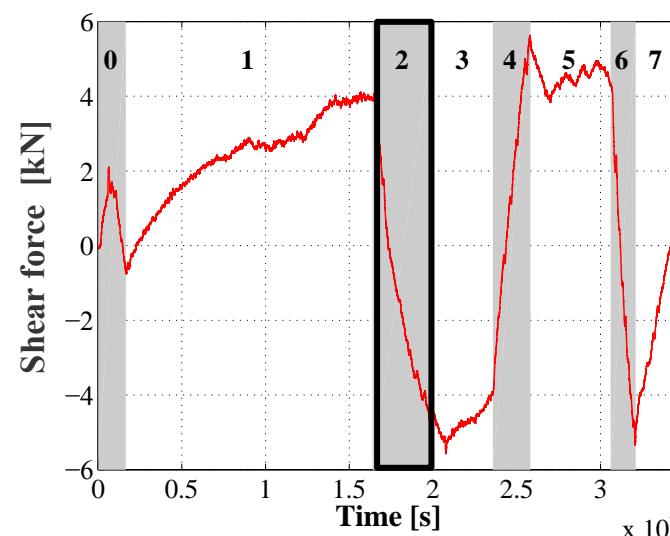
0. Elastic load-unload
1. Rotation & shear +
2. Shear -
3. Rotation
4. Shear +
5. Rotation
6. Shear -
7. Traction



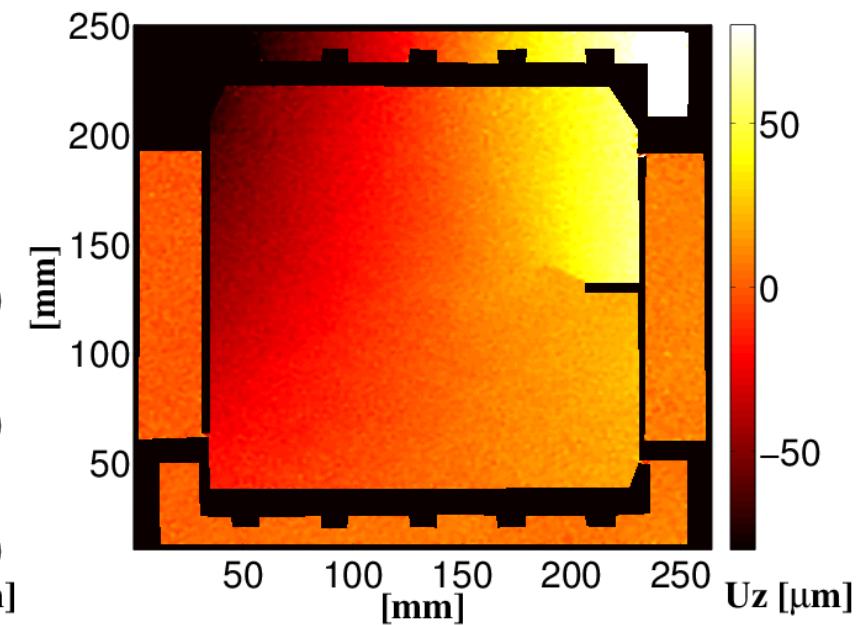
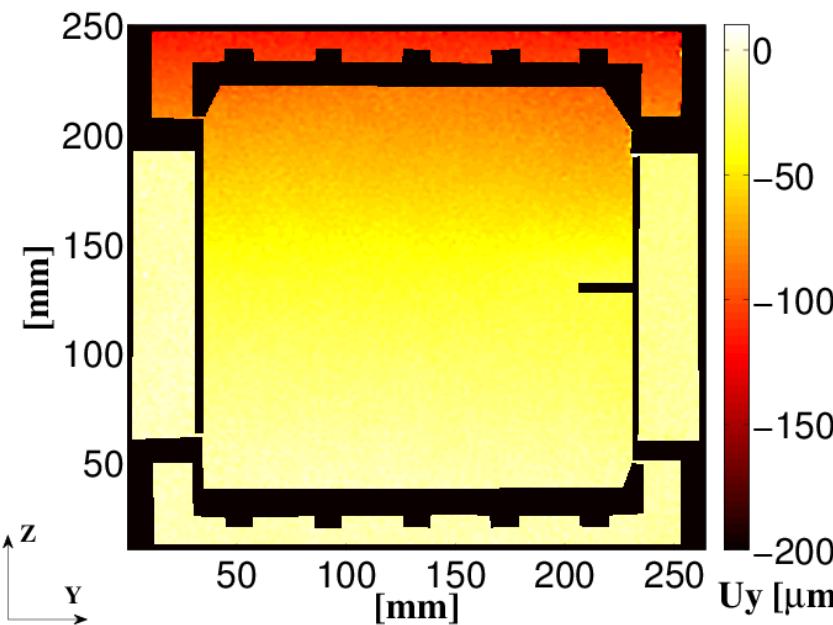
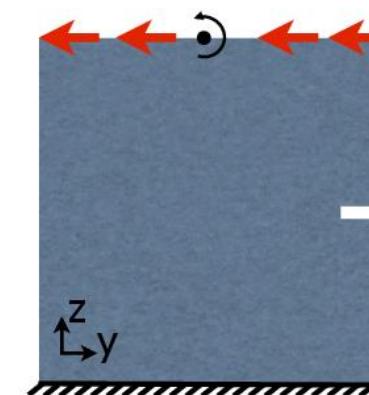
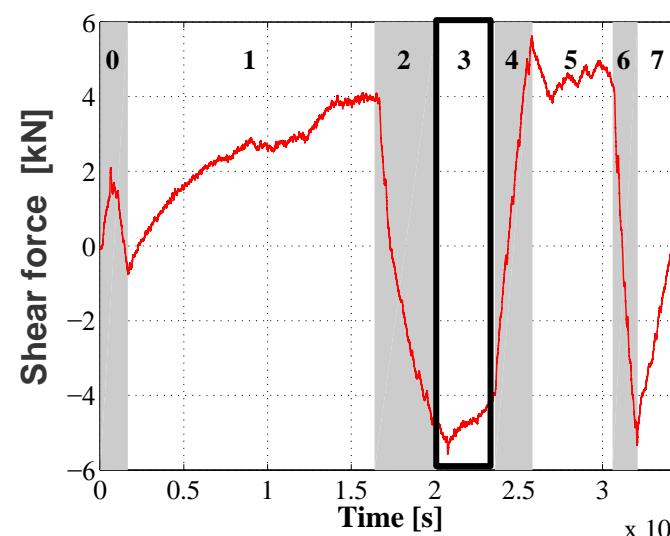
Rotation + Shear



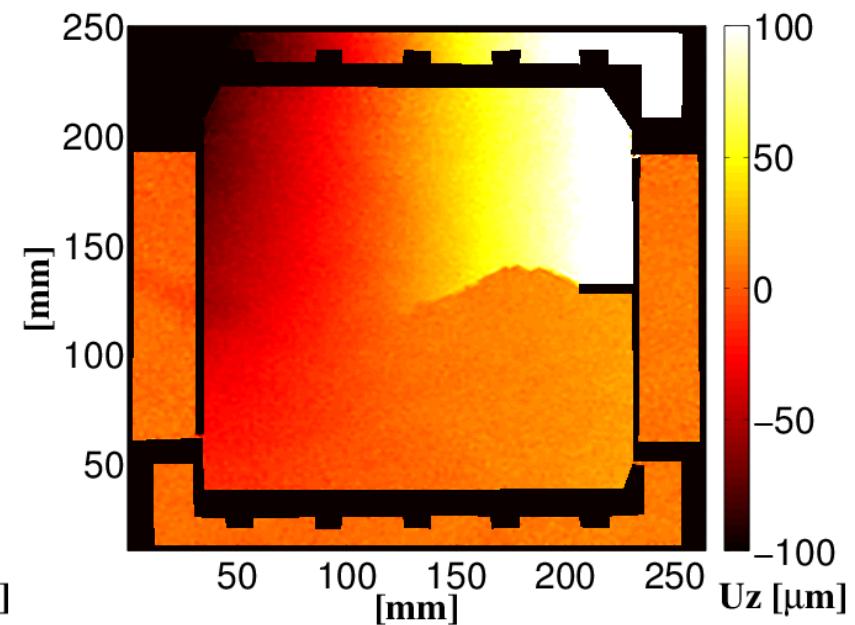
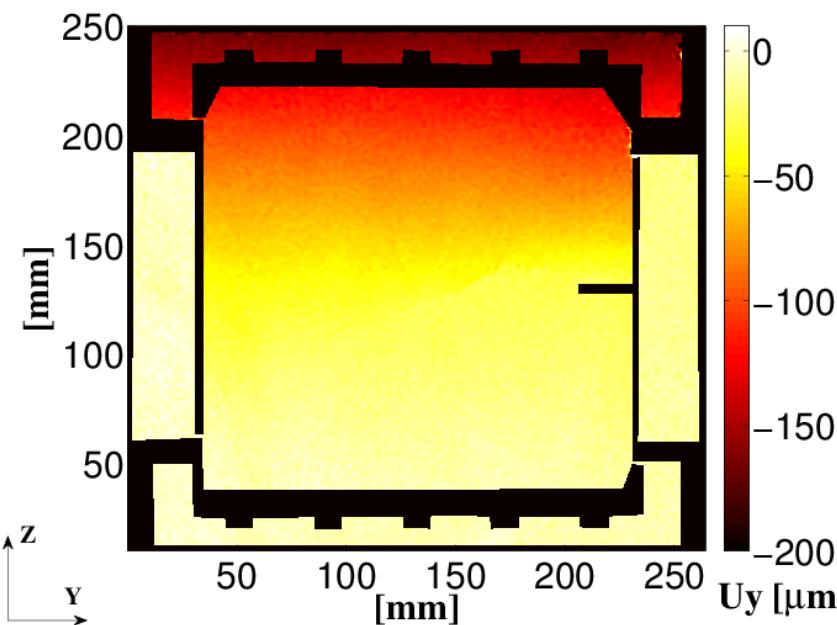
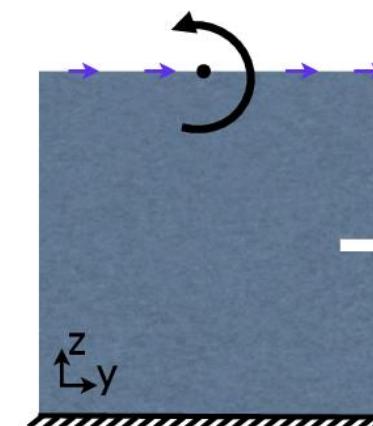
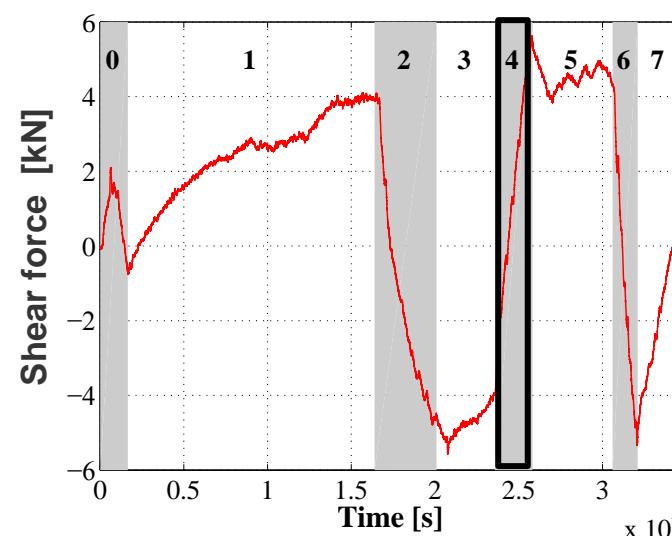
Shear



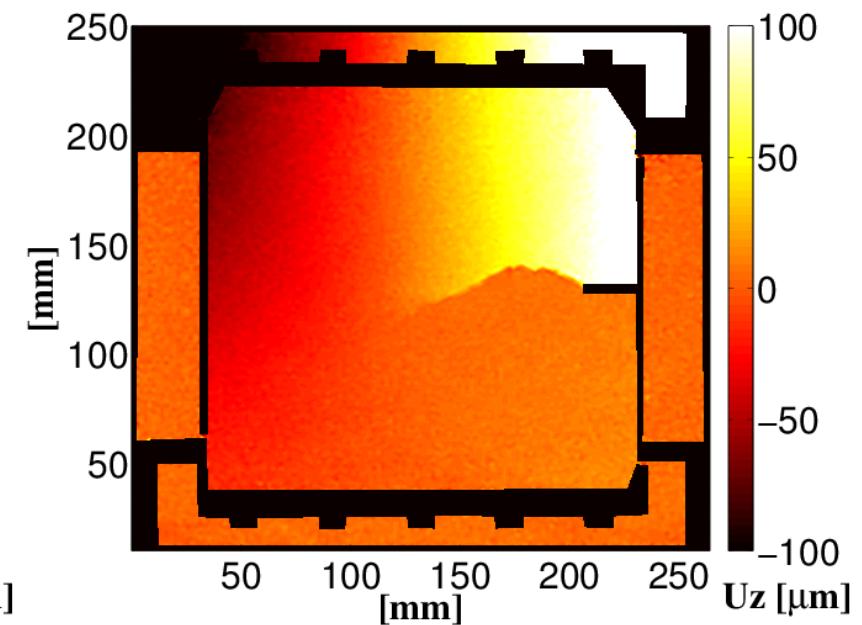
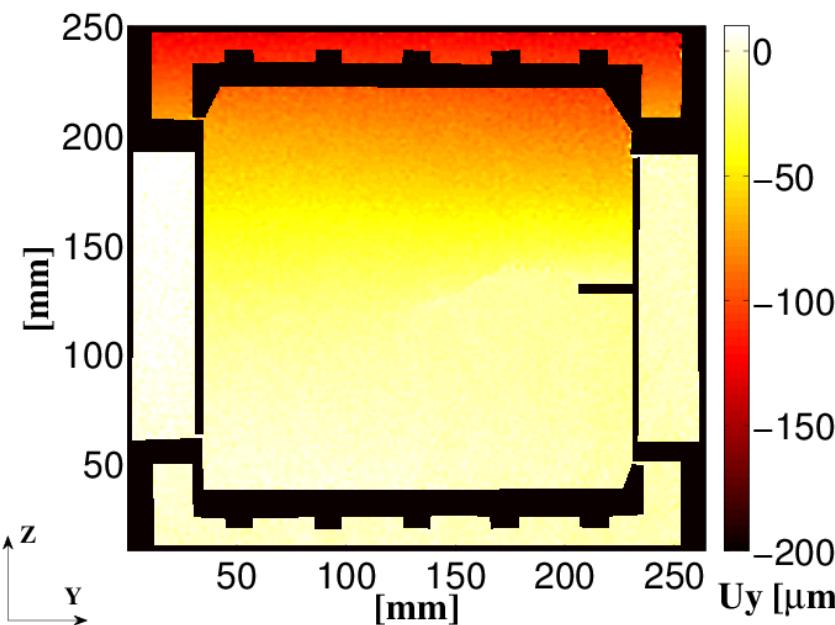
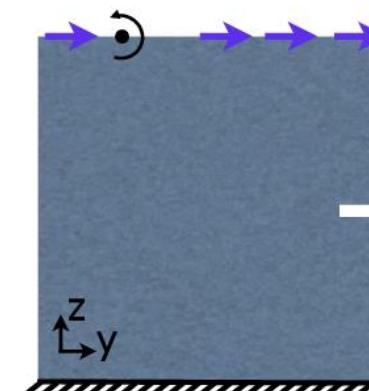
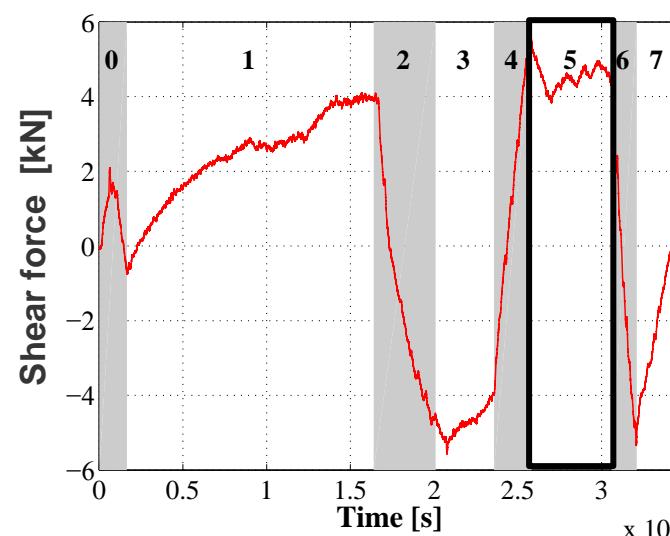
Rotation



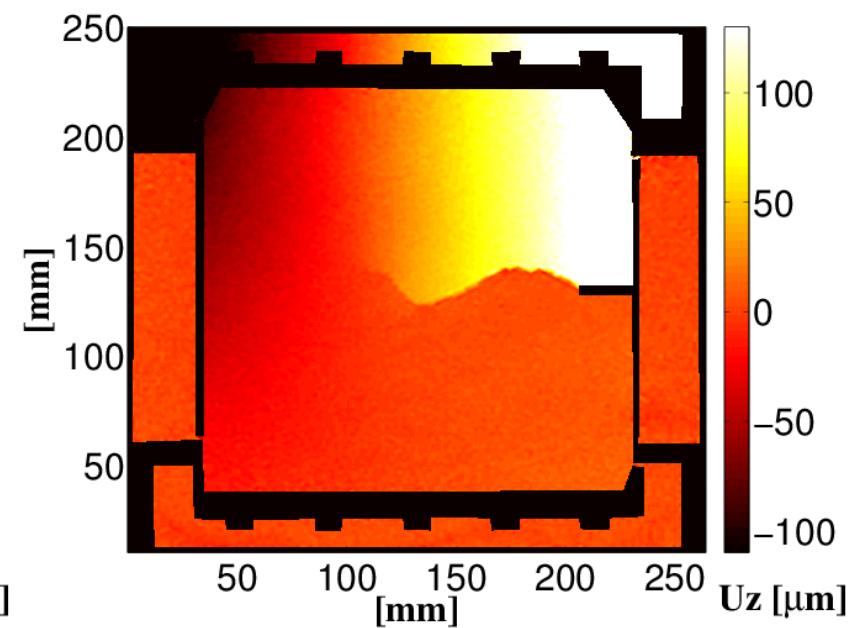
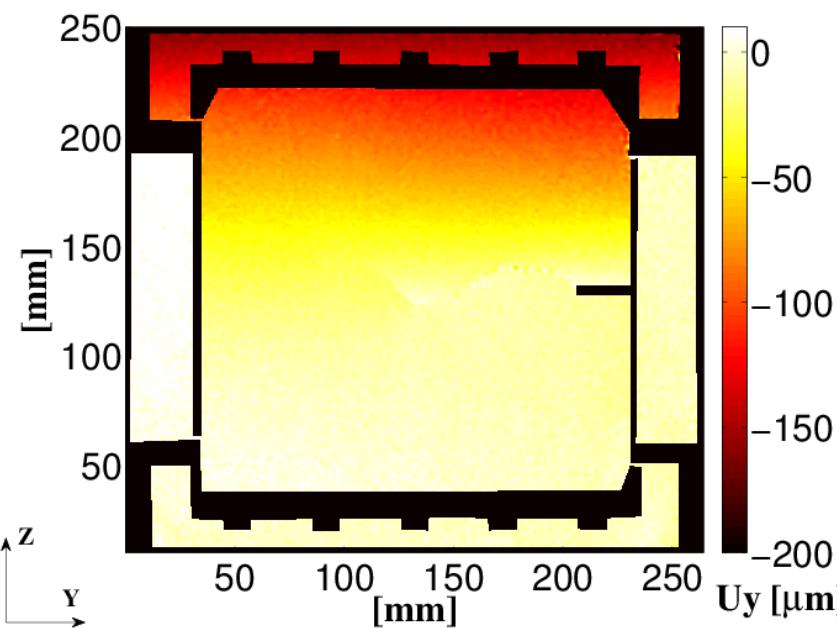
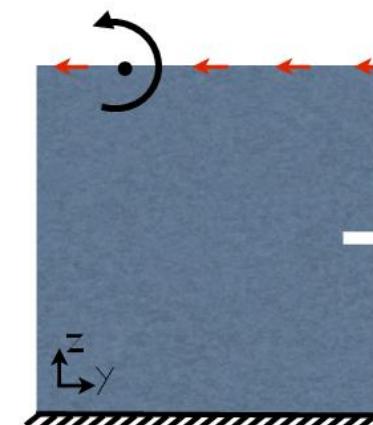
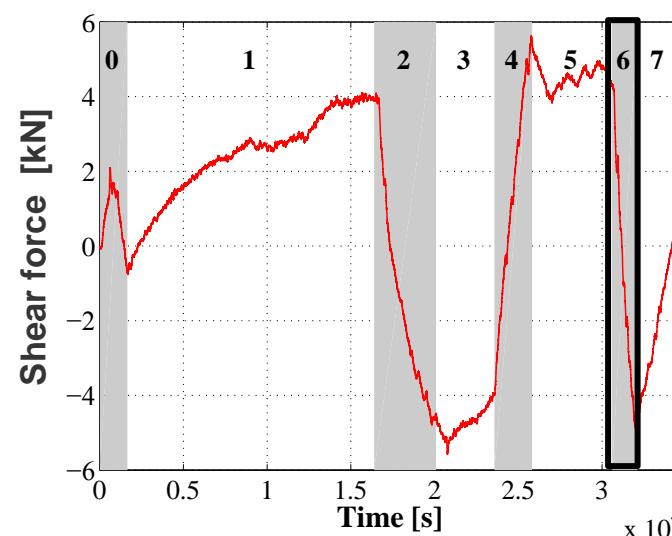
Shear



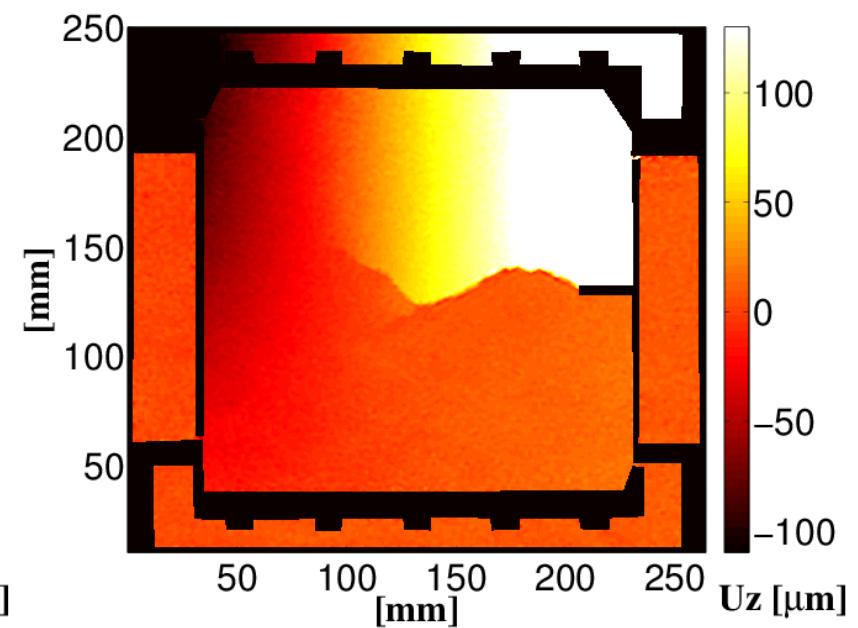
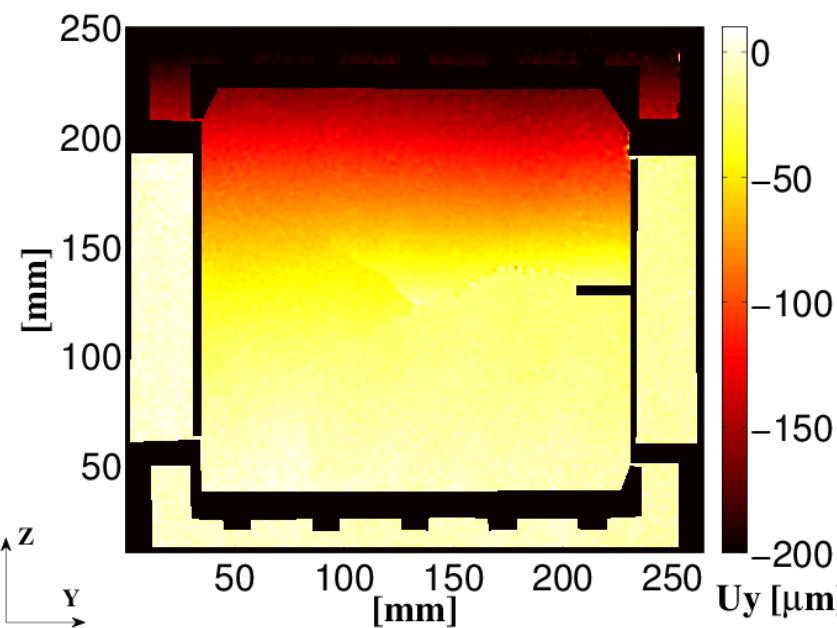
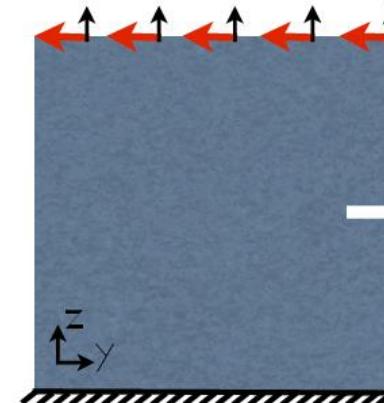
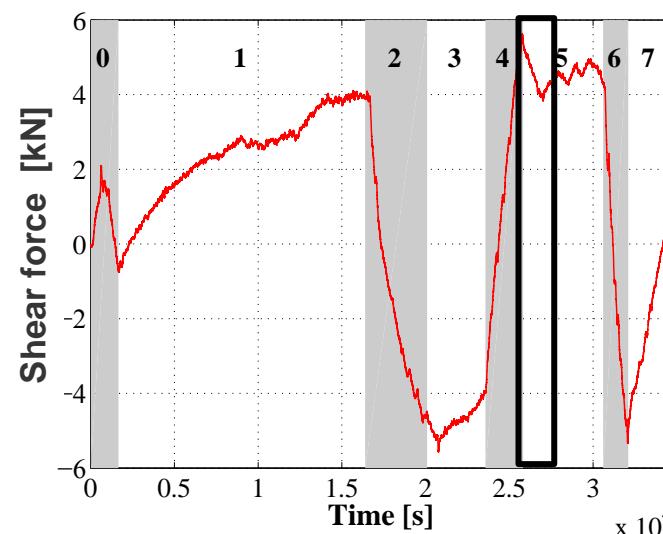
Rotation



Shear

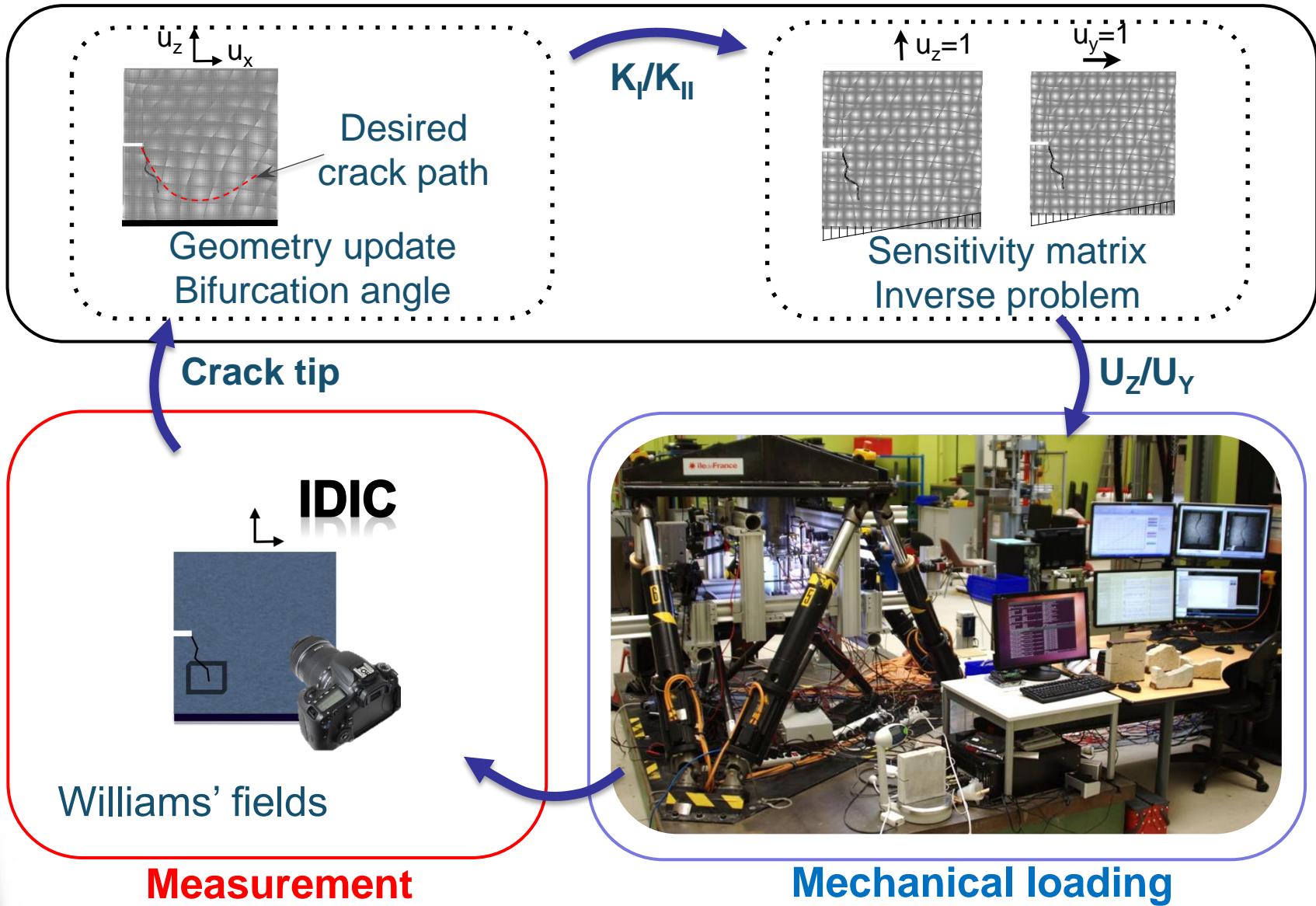


Tension

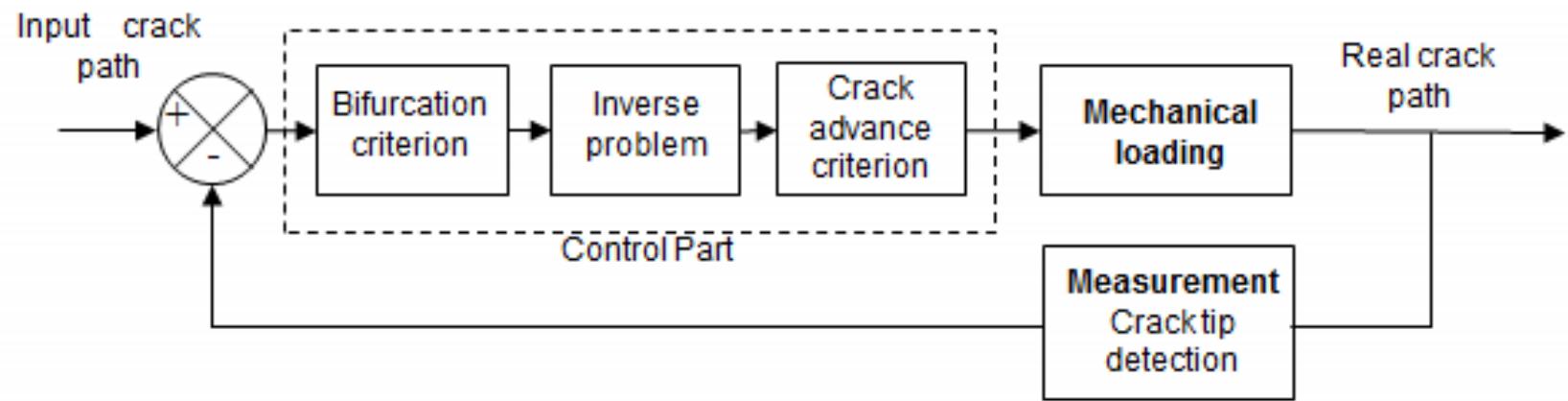


Hybrid Test

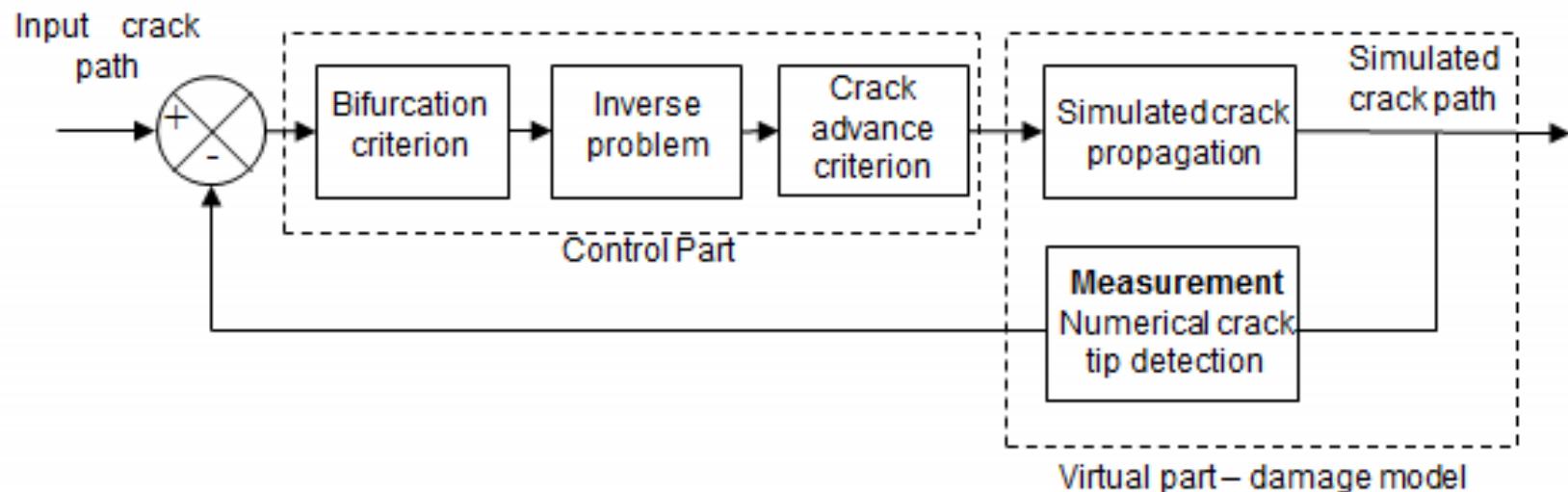
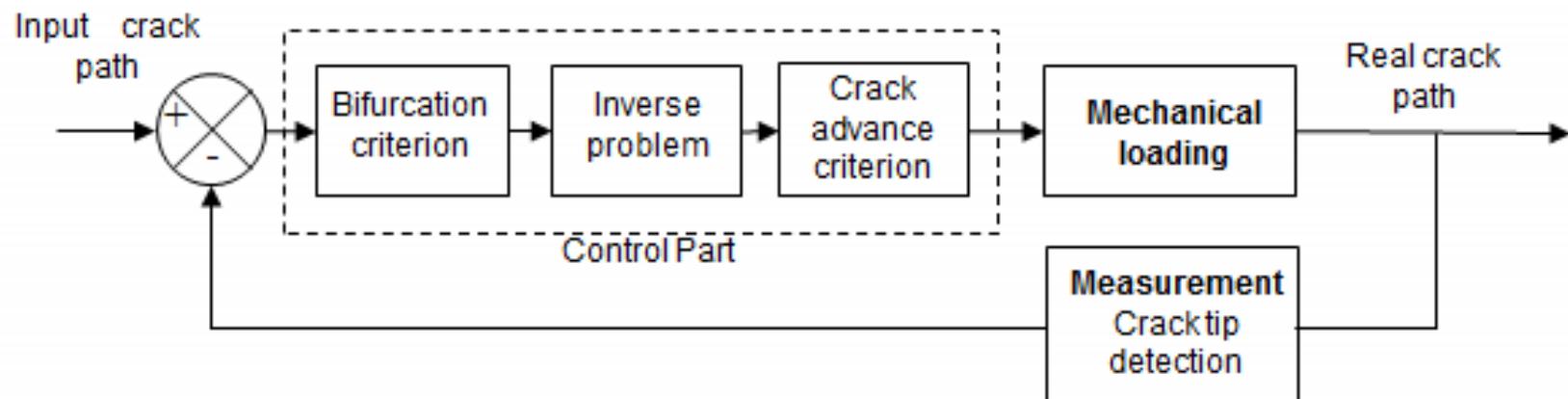
Control - LEFM



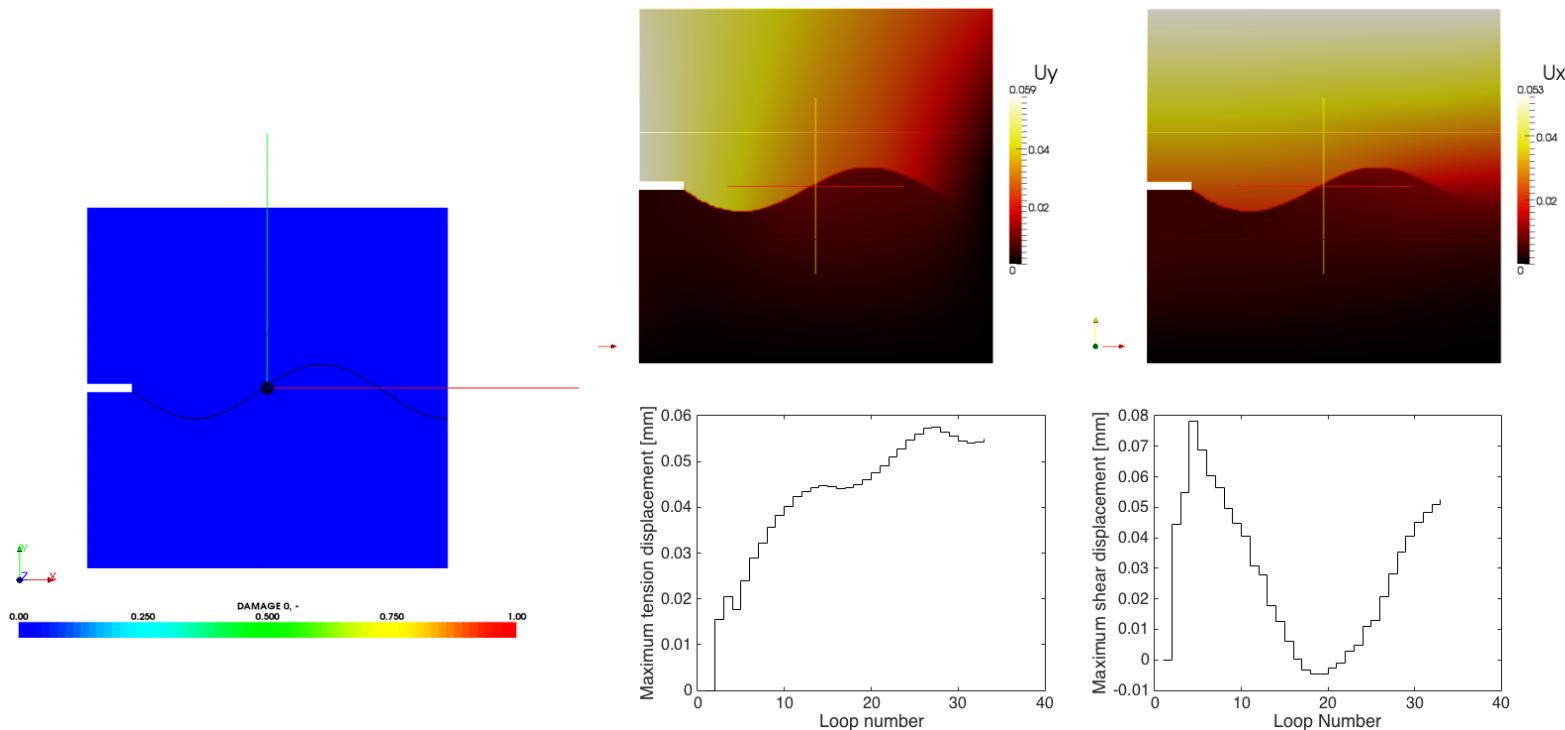
Hybrid Test



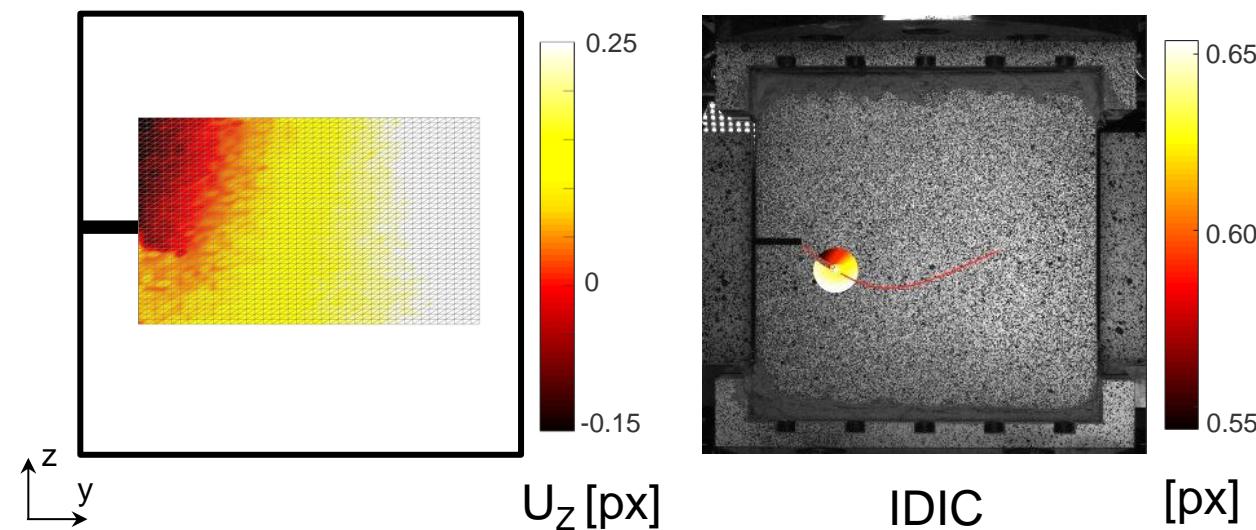
Virtual Hybrid Test*



Virtual Hybrid Test



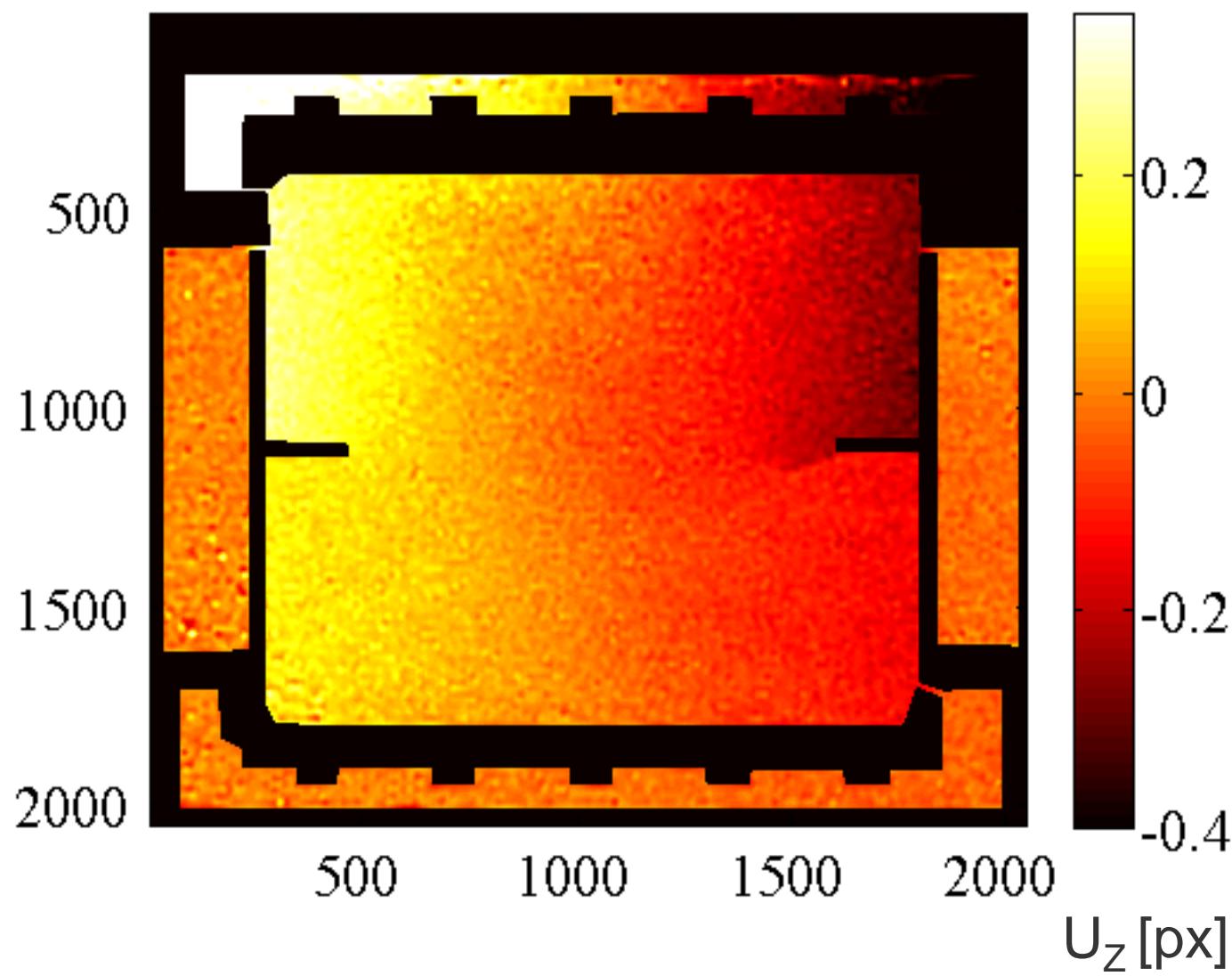
Hybrid Test



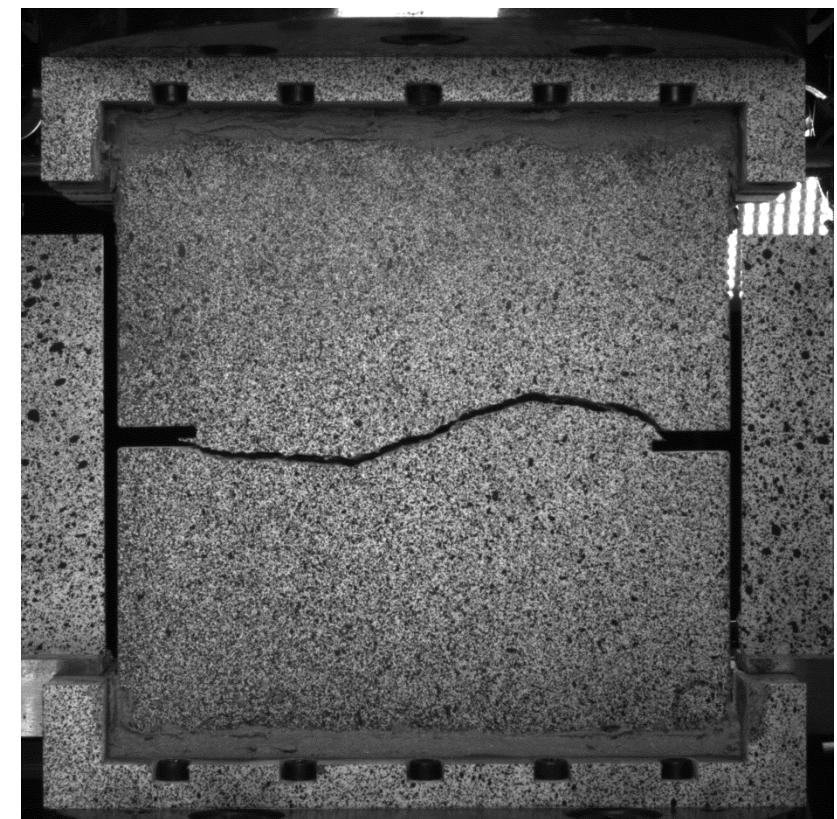
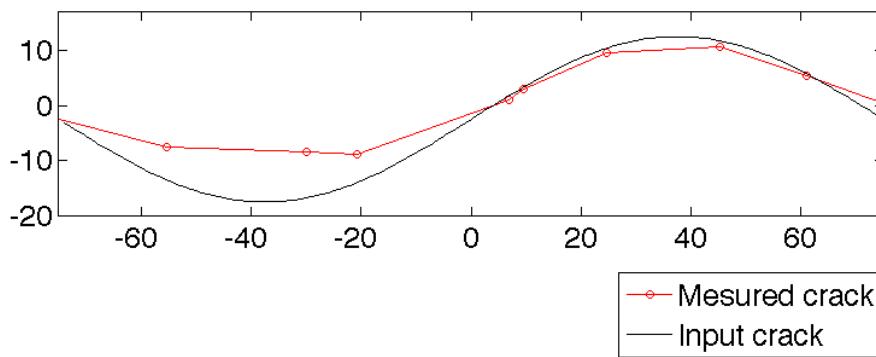
Crack tip detection

- IDIC: Williams [1957] fields (LEFM)
[Roux et al., 2006] for straight cracks
[Réthoré, 2015] for curved cracks

Hybrid Test



Hybrid Test



Summary

- Evaluation of damage in brittle materials via **DIC** and **DVC**
- Design of discriminating experiments (e.g., concrete)
 - **DIC**
 - **benchmark**
 - **DIC-driven tests**
 - **optimized tests**



**Vielen Dank für
Ihre Aufmerksamkeit!**