

Algorithmic Aspects of WQO Theory

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Complexity Upper Bounds

- Goal:
- Many algorithms rely on wqo arguments to prove termination (we saw Abdulla's backwards search).
 - We want to obtain complexity upper bounds for such algorithms.

Recall:

$(A, \leq)$ is a wqo iff every infinite sequence $(a_i)_{i \in \mathbb{N}}$ contains an increasing pair
 $a_i \leq a_j$ with $i < j$.

We call sequences with an increasing pair good,
and sequences without bad.

Hence, every infinite sequence over a wqo is good,
and every bad sequence over a wqo is finite.

Key question: How long can bad sequences be?

Contribution: Techniques to bound the length.

The very generic/powerful.

↳ Only the dimension / wqo
and the complexity
of operations matter.

Example:

SIMPLE (a, b) :

$c = 1$;

while $a > 0 \wedge b > 0$ do

$l: (a, b, c) = (a-1, b, 2c)$

$+ r: (a, b, c) = (2c, b-1, 1)$

od

One can check that, in any run,

the sequence of values taken by a and b ,

$$(a_0, b_0), (a_1, b_1), \dots$$

is a bad sequence over $(\mathbb{N}^2, \leq)$.

Since this is a wgo by Dickson's lemma,

the bad sequence is finite and so

$\text{SIMPLE}(a_0, b_0)$ terminates.

How long can it run?

Say $(a_0, b_0) = (2, 7)$.

$$(2, 3, 2^0) \xrightarrow{L} (1, 3, 2^2) \xrightarrow{r} (2^2, 2, 1)$$

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$$\xrightarrow{L^{2^2-1}} (2^{2^2}, 1, 1)$$

$$\xrightarrow{L^{2^2-1}} (2^{2^{2^2}}, 0, 1)$$

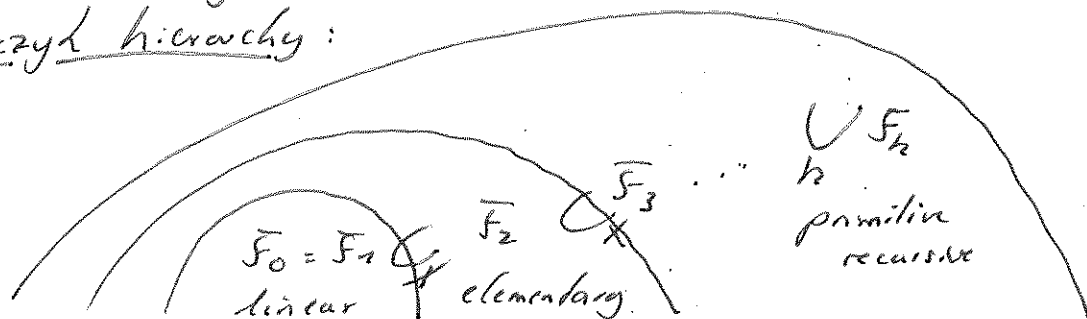
Has length

$$2 + 2^2 + 2^{2^2}$$

This is non-elementary in the size of the initial values.

- Fact:
- Linear operations and dimension 2 yield complexities beyond the elementary hierarchies.
 - Distinctions between time and space complexity and non-determinism vs. determinism become irrelevant.
 - A hierarchy of non-elementary complexity useful here is this

Gregorczyk hierarchy:



In the case of SIMPLE, there is a function in F_3 that bounds the length of all runs.

The Length of Controlled Bad Sequences

Problem: Consider $(\mathbb{N}^2, \leq)$.

Then $\begin{matrix} x_0 & & x_1 \\ \text{"} & & \text{"} \end{matrix}$

$(0, 1), (1, 0), (L-2, 0), (L-2, 0), \dots$

is a bad sequence of length $L+1$.

for every $L \in \mathbb{N}$.

We have an uncontrolled jump

from x_0 to an arbitrarily high x_1 .

To obtain bounds on the length of bad sequences, we need to assume programs transform states in a controlled way.

Definition:

Let $(R, \leq)$ be a wgo.

R norm is a function $| \cdot | : R \rightarrow \mathbb{N}$

so that $R_{\leq n} := \{a \in R \mid |a| \leq n\}$ is finite f.a.n.e.

We call $(R, \leq, | \cdot |)$ a normed wgo.

As an example, on $(\mathbb{N}^2, \leq)$ we have $|(m, n)|_{\mathbb{N}^2} := \max\{m, n\}$.

We assume there is a control function $g : \mathbb{N} \rightarrow \mathbb{N}$

that bounds the growth of elements

when we go through a sequence $(a_i)_{i \in \mathbb{N}}$ in R .

We assume g is strictly increasing, $g(x+1) \geq g(x) + 1$.

- A sequence $(a_i)_{i \in \mathbb{N}}$ on $(A, \leq, 1.1)$ is (g, n) -controlled with $n \in \mathbb{N}$, if for all $i \in \mathbb{N}$,

$$|a_i| \leq g^i(n) \quad \text{with } g^0 = \text{id}, g^{i+1} = g \circ g^i.$$

The value n is also called initial norm.

Example:

SIMPLE is (g, n) -controlled

$$\text{with } g(x) = 2x$$

$$n = \max \{a_0, b_0\}.$$

Definition:

- We let $[k]$ be the wgo $(\{0, \dots, k-1\}, \leq, 1.1_{[k]})$

with $\leq$ the usual $\leq$ on natural numbers

$$|j|_{[k]} = j.$$

- We let T_h be the wgo $(\{a_0, \dots, a_{h-1}\}, \leq, 1.1_{T_h})$

$$\text{with } |a_j|_{T_h} = 0.$$

Length function:

For every wgo $(A, \leq, 1.1_A)$,

there is a longest (g, n) -controlled bad sequence:

↳ organize these sequences into a tree
by sharing prefixes,

↳ the outdegree is bounded by $|A| \leq g^i(n)$
for a node at depth i ,

↳ the depth is bounded thanks to the wgo.

By König's lemma, the tree is finite.

Let $L_{g,n,A}$ be its height,

which is the length of the longest

(g,n) -controlled bad sequence in A .

We are interested in this length as a function in n :

$$L_{g,A}(n) := L_{g,n,A}.$$

We then obtain complexity bounds on $L_{g,A}$.

Remark:

$L_{g,A}(n)$ is monotonic in n and in g .

If $g(x) \leq h(x)$ f.a. x ,

then every (g,n) -controlled bad sequence
is also (h,n) -controlled.

Hence, $L_{g,A}(n) \leq L_{h,A}(n)$ f.a. n .

Polynomial MWQOs

Definition:

We call two MWQOs $(A, \leq_A, |\cdot|_A)$ and $(B, \leq_B, |\cdot|_B)$ isomorphic,

$A \cong B$, if there is a bijection $f: A \rightarrow B$ so that

$\forall a_1, a_2 \in A. \quad a_1 \leq_A a_2 \iff f(a_1) \leq_B f(a_2)$

$$|a_1|_A = |f(a_1)|_B.$$

Note that then $L_{g,A} = L_{g,B}$.

Examples:

- 1) $[0] \equiv T_0$ // no elements, called empty wgo
- 2) $[1] \equiv T_1$ since $|a_0|_{T_1} = 0 = |0|_{[1]}$. // called singleton wgo
- 3) $[2] \neq T_2$: The ordering is not isomorphic:
 $0 \leq_{[2]} 1$ but $a_0 \not\leq_{T_2} a_1$.

The norm is not the same:

$$|1|_{[2]} = 1 \text{ but } |a_1|_{T_2} = 0.$$

The controlled bad sequences differ:

a_1, a_0 is $(g, 0)$ -controlled in T_2
only 0 is $(g, 0)$ -controlled in $[2]$.

Hence, also the length functions are different

Definition: Let $(A_1, \leq_{A_1}, |\cdot|_{A_1})$ and $(A_2, \leq_{A_2}, |\cdot|_{A_2})$ be two wgos.

The disjoint sum of A_1 and A_2 is

$$(A_1 + A_2, \leq_{A_1 + A_2}, |\cdot|_{A_1 + A_2})$$

w.th

$$A_1 + A_2 := (\{1\} \times A_1) \cup (\{2\} \times A_2)$$

$$(i, a) \leq_{A_1 + A_2} (j, b), \text{ if } i = j \text{ and } a \leq_{A_i} b$$

$$|(i, a)|_{A_1 + A_2} := |a|_{A_i}.$$

The Cartesian product

$$(A_1 \times A_2, \leq_{A_1 \times A_2}, |\cdot|_{A_1 \times A_2})$$

is defined by

$$(a_1, a_2) \leq_{A_1 \times A_2} (b_1, b_2), \text{ if } a_1 \leq_{A_1} b_1 \text{ and } a_2 \leq_{A_2} b_2.$$

$$|(a_1, a_2)|_{A_1 \times A_2} := \max \{ |a_1|_{A_1}, |a_2|_{A_2} \}.$$

That this is a wgo is Dickson's lemma.

• We write $A \cdot h$ for $\underbrace{A + A + \dots + A}_{h \text{ times}}$.

Then $T_h \equiv T_1 \cdot h$, in particular $T_0 \equiv A \cdot 0$.

• We write A^d for $\underbrace{A \times A \times \dots \times A}_{d \text{ times}}$.

Then $A^0 \equiv T_1$, the singleton set with 1 in it, the size is 0.

• We also need the natural numbers $(N, \leq_N, 1, 1_N)$ with $1h1_N = h$.

Definition:

The set of polynomial nrgos is the smallest set of nrgos with

- T_0, T_1, N in it and
- closed under $+$ and $\times$.

Example:

The configurations of a d -dimensional VBS are states Q with $|Q| = p$ it is isomorphic to $N^d \times T_p$, which is a polynomial nrgo.

Lemma:

The class of nrgos factorized along $\equiv$ forms a commutative semiring:

$(NWQOs / \equiv, +, T_0)$ is a commutative monoid

$(NWQOs / \equiv, \times, T_1)$ is a commutative monoid

$T_0 \times A \equiv T_0 \equiv A \times T_0$, T_0 is absorbing for $\times$

$A \times (B + C) \equiv (A \times B) + (A \times C)$ Distributivity.

Remark:

By the previous lemma,
every polynomial ring can be brought into
polynomial normal form (PNF):

$$P \equiv N^{d_1} + \dots + N^{d_m}, \quad m, d_1, \dots, d_m \in \mathbb{N}$$

Recall that $N^0 \equiv T_1$.

We will also denote T_0 by 0 and T_1 by 1,
and we will only be working with polynomial rings in PNF.

Example:

$$\begin{aligned} N^d \times T_p &\equiv N^d \times (T_1 + \dots + T_1) \\ &\quad \text{p-times} \\ &\equiv (N^d \times T_1) + \dots + (N^d \times T_1) \\ &\equiv N^d + \dots + N^d \\ &= p \cdot N^d \end{aligned}$$

Subrecursive Functions

Goal: Study in slightly more detail
functions that we non-elementary but primitive recursive.

Definition:

The Gödel hierarchy hierarchy $(F_h)_{h \in \mathbb{N}}$

is a hierarchy of

classes of primitive recursive functions:

with

$$\bigcup_{h \in \mathbb{N}} F_h = PR \quad \leftarrow \text{all primitive recursive functions.}$$

We have:

$F_0 = F_1 =$ linear functions.

$F_2 =$ elementary functions. It starts from level 1

The definition uses the h -th fast growing function $F_h: \mathbb{N} \rightarrow \mathbb{N}$

$$F_0(x) := x+1$$

$$F_{h+1}(x) := F_h^{x+1}(x) := \overbrace{F_h(\dots (F_h(x)) \dots)}^{x+1 \text{ times}}.$$

Then $F_h := \{ f \mid \exists i. f \text{ is computed in time/space } \leq F_i \}$.

Example:

$$\cdot \quad \bar{F}_1(x) = \bar{F}_0^{x+1}(x)$$

$$= \underbrace{((x+1)+1)+1}_{x+1}$$

$$= x + (x+1) \cdot 1 = 2x + 1$$

$$\cdot \quad \bar{F}_2(x) = \bar{F}_1^{x+1}(x)$$

$$= \underbrace{2(2(2x+1)+1)+1}_{x+1}$$

$$= 2^{x+1} \cdot x + \sum_{i=0}^x 2^i$$

$$= 2^{x+1} \cdot x + 2^{x+1} - 1$$

$$= 2^{x+1}(x+1) - 1$$

$$\cdot \quad \bar{F}_3(x) > 2^{2^{\dots^2}} \left\{ \begin{array}{l} x \text{ - times} \end{array} \right.$$

Remark:

• The functions $\bar{F}_k$ are honest:

they can be computed in time space elementary in $\bar{F}_k$,
even in space $O(\bar{F}_k)$:

This means $\bar{F}_k \in \mathcal{F}_k$.

$$\bar{F}_k(\dots(\bar{F}_k(\bar{F}_{k-2}(\dots(\bar{F}_{k-2}(\bar{F}_{k-2}(\dots$$

• All functions $f \in \mathcal{F}_k$

are eventually (for large enough inputs)

bounded by $\bar{F}_{k+1}$.

Hence, $\mathcal{F}_{k+1} \not\subseteq \mathcal{F}_k$.

Upper Bounds for Dickson's Lemma:

Theorem (Length Function Theorem): Let g be a total function bounded by a function in $\mathcal{F}_\delta$, $\delta \geq 2$. Let $d, p \geq 0$.

-g- Then $L_{g, \text{nd}_x T_p}$ is bounded by $\mathcal{F}_{\delta+d}$.

Example (Shadow memory):

SIMPLE(a, b):

$c := 1;$

while $a > 0 \wedge b > 0$ do

l: $(a, b, c) := (a-1, b, 2c)$

+ r: $(a, b, c) := (2c, b-1, 1)$

od

The bad sequences in SIMPLE over $\mathbb{N}^3$
are also bad sequences over $\mathbb{N}^2$
when we only consider a and b .

The control function for this sequence over $\mathbb{N}^2$

is $g(x) = 2x$ in $\mathbb{F}_1$. ←

Note that this is not immediate:

$$(5, 1, 1) \xrightarrow{l^4} (1, 1, 2^4) \xrightarrow{r} (2^5, 0, 1)$$

Although the r transition changes
the value of a drastically,
we have

$$\begin{aligned} 2^5 &\leq g^5(5) \\ &= 2 \cdot 2 \cdot 2 \cdot 2 \cdot 2 \cdot 5 = 2^5 \cdot 5. \end{aligned}$$

The length function theorem

applied with $\delta = 1$ and $\rho = 1$

yields a function in $\mathbb{F}_3$

that bounds the length of all runs in SIMPLE.

What is needed to hide some part of the state for the length estimation?

↳ Hiding has to preserve the bad sequences.

If the original sequence was bad,

so should be the sequence resulting from hiding.

↳ The control function has to be large enough to cover the effect that the hidden part has on the non-hidden part of the state when taking a transition.