## A toy model for hysteretic phase transitions MICHAEL HERRMANN (joint work with Michael Helmers, University of Bonn)

The one-dimensional lattice ODE

(1) 
$$\dot{u}_j = p_{j+1} - 2p_j + p_{j-1}$$
 with  $p_j = u_j - \operatorname{sign} u_j$ 

admits solutions with propagating phase interfaces and provides a microscopic justification for macroscopic hysteresis models. Here, the two *phases* correspond to the sets  $\{u < 0\}$  and  $\{u > 0\}$ , on which the bistable function  $u \mapsto u - \operatorname{sign} u$  is strictly increasing.

**Microscopic dynamics.** For a finite system with  $N < \infty$  particles and either periodic or Neumann boundary conditions, equation (1) can be regarded is a microscopic H<sup>-1</sup>-gradient flow for u. In particular, it satisfies the energy balance

$$\dot{\mathcal{E}}(t) = -\mathcal{D}(t), \quad \mathcal{E} := \frac{1}{2} \sum_{j} p_{j}^{2}, \quad \mathcal{D} := \sum_{j} (p_{j+1} - p_{j})^{2},$$

so there is a strong tendency to reach a state with small dissipation. However, due to phase transitions (one of the  $u_j$ 's changes sign) there exist small time intervals with huge dissipation and strong microscopic fluctuations, see Figures 1 and 2 for an illustration.

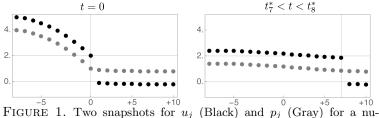


FIGURE 1. Two snapshots for  $u_j$  (Black) and  $p_j$  (Gray) for a numerical single-interface solution with 20 particles: The phase interface (vertical line) propagates to the right since the particles undergo a phase transition one after another.

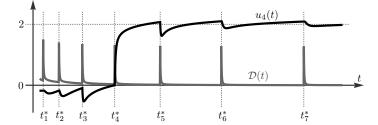


FIGURE 2. Evolution of  $u_4$  and the (rescaled) dissipation  $\mathcal{D}$  for the simulation from Figure 1; the particle j undergoes a phase transition at time  $t_j^*$ .

Macroscopic dynamics. The parabolic scaling limit

$$\tau := \varepsilon^2 t, \qquad \xi := \varepsilon j$$

has been investigated in [1] for a system with infinitely many particles and under certain assumptions on the microscopic initial data; the main result can be formulated as follows: The discrete *p*-data converge as  $\varepsilon \to 0$  strongly to a limit function *P*, which is uniquely determined by the hysteretic free boundary problem

(2) 
$$\partial_{\tau} \left( P(\tau, \xi) + \mu(\tau, \xi) \right) = \partial_{\xi}^2 P(\tau, \xi), \qquad \mu(\cdot, \xi) = \mathcal{R} \left[ P(\cdot, \xi) \right].$$

Here,  $\mathcal{R}$  abbreviates the hysteresis operator from Figure 3 and the limit U of the u-data satisfies  $U = P + \mu$ . The well-posedness of the initial value problem to (2) has been proven in [2].

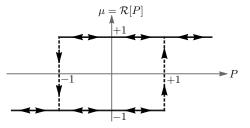


FIGURE 3. The relay operator  $\mathcal{R}$  describes the hysteresis of phase interfaces in the macroscopic scaling limit.

## References

- M. Helmers, M. Herrmann: Interface dynamics in discrete forward-backward diffusion equations, SIAM Multiscale Model. Simul., vol. 11(4), pp. 1261–1297, 2013.
- [2] A. Visintin: Quasilinear parabolic P.D.E.s with discontinuous hysteresis, Ann. Mat. Pura Appl., vol. 185(4), pp. 487–519, 2006.